

# Low Power Clock Chip for Serverworks HT2400 Servers

#### **Recommended Application:**

Serverworks HT2400-based systems using AMD Opteron processors

#### **Output Features:**

- 7 Pairs of AMD Low Power K8 Greyhound compliant clocks
- 7 Pair of SRC/PCI Express\* Gen 2 clocks
- 3 14.318 MHz REF clocks including 1 free-running
- 2 48MHz clocks
- 2 PCI 33 MHz clocks
- 2 25MHz clocks

#### Features:

- Spread Spectrum for EMI reduction
- Outputs may be disabled via SMBus
- M/N programming via SMBus
- PCIe clocks meet PCIe Gen 2.
- · Low Power differential outputs

#### **Functionality**

			CPU
FS2	FS1	FS0	(MHz)
0	0	0	Hi-Z
0	0	1	X/6
0	1	0	180.00
0	1	1	220.00
1	0	0	100.00
1	0	1	133.33
1	1	0	Reserved
1	1	1	200.00

#### **Power Groups**

Pin N	umber	Description		
VDD GND				
8	11	48MHz Clocks		
64	61	25MHz Clocks		
14	17	33 MHz PCI Clocks		
20	21	Analog Core		
36, 28	35, 27	PCIe clocks		
55, 47	54, 46	K8G CPU Clocks		
3	7	REF Clocks, Xtal Osc.		

#### **Pin Configuration**



**Pin Description** 

PIN#	PIN NAME	TYPE	DESCRIPTION				
1	X1	IN	Crystal input, Nominally 14.318MHz.				
2	X2	OUT	Crystal output, Nominally 14.318MHz				
3	VDDREF_STB	PWR	Ref, XTAL power supply, nominal 3.3V standby power				
4	REF0_RUN_2x	OUT	14.318MHz Free Running XTAL Output. This output runs as long as standby VDD is applied to the part. Default drive is 2 loads.				
5	FS1/REF1_2x	I/O	Frequency select latch input pin / 14.318 MHz reference clock. Default 2 load drive.				
6	FS2/REF2_2x	I/O	Frequency select latch input pin / 14.318 MHz reference clock. Default 2 load drive.				
7	GNDREF	PWR	Ground pin for the REF outputs.				
8	VDD48	PWR	Power pin for the 48MHz output.3.3V				
9	48MHz_0_2x	OUT	48MHz clock output. Default 2 load drive strength				
10	48MHz_1_2x	OUT	48MHz clock output. Default 2 load drive strength				
11	GND48	PWR	Ground pin for the 48MHz outputs				
12	SCLK	IN	Clock pin of SMBus circuitry, 5V tolerant.				
13	SDATA	I/O	Data pin for SMBus circuitry, 3.3V tolerant.				
14	VDDPCI	PWR	Power supply for PCI clocks, nominal 3.3V				
15	PCICLK0_2x	OUT	3.3V PCI clock output. Default 2 load drive strength.				
16	PCICLK1_2x	OUT	3.3V PCI clock output. Default 2 load drive strength.				
17	GNDPCI	PWR	Ground pin for the PCI outputs				
18	CLKPWRGD/PD#	IN	This 3.3V LVTTL input is a level sensitive strobe used to determine when latch inputs are valid and are ready to be sampled. This is an active high input. / Asynchronous active low input pin used to power down the device into a low power state.				
19	GND	PWR	Ground pin.				
20	VDDA	PWR	3.3V power for the PLL core.				
21	GNDA	PWR	Ground pin for the PLL core.				
22	GND	PWR	Ground pin.				
23	PCleT_L0	OUT	True clock of 0.8V differential push-pull PCI_Express pair (no 50ohm resistor to GND needed)				
24	PCIeC_L0	OUT	Complement clock of 0.8V differential push-pull PCI_Express pair. (no 50ohm resistor to GND needed)				
25	PCleT_L1	OUT	True clock of 0.8V differential push-pull PCI_Express pair (no 50ohm resistor to GND needed)				
26	PCleC_L1	OUT	Complement clock of 0.8V differential push-pull PCI_Express pair. (no 50ohm resistor to GND needed)				
27	GND	PWR	Ground pin.				
28	VDDPCle	PWR	Power supply for PCI Express clocks, nominal 3.3V				
29	PCleT_L2	OUT	True clock of 0.8V differential push-pull PCI_Express pair (no 50ohm resistor to GND needed)				
30	PCleC_L2	OUT	Complement clock of 0.8V differential push-pull PCI_Express pair. (no 50ohm resistor to GND needed)				
31	PCleT_L3	OUT	True clock of 0.8V differential push-pull PCI_Express pair (no 50ohm resistor to GND needed)				
32	PCIeC_L3	OUT	Complement clock of 0.8V differential push-pull PCI_Express pair. (no 50ohm resistor to GND needed)				



**Pin Description (continued)** 

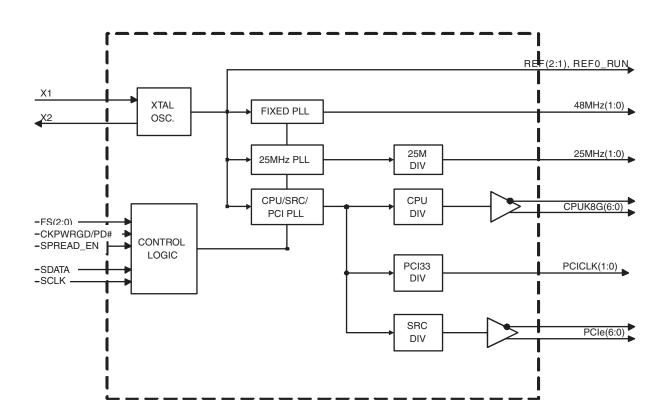
PIN#	escription (continued) PIN NAME	TYPE	DESCRIPTION
			Complement clock of 0.8V differential push-pull PCI_Express pair. (no
33	PCIeC_L4	OUT	50ohm resistor to GND needed)
34	PCleT_L4	OUT	True clock of 0.8V differential push-pull PCI_Express pair (no 50ohm
34			resistor to GND needed)
35	GND	PWR	Ground pin.
36	VDDPCle	PWR	Power supply for PCI Express clocks, nominal 3.3V
37	PCIeC_L5	OUT	Complement clock of 0.8V differential push-pull PCI_Express pair. (no 50ohm resistor to GND needed)
38	PCIeT_L5	OUT	True clock of 0.8V differential push-pull PCI_Express pair (no 50ohm resistor to GND needed)
39	PCIeC_L6	OUT	Complement clock of 0.8V differential push-pull PCI_Express pair. (no 50ohm resistor to GND needed)
40	PCleT_L6	OUT	True clock of 0.8V differential push-pull PCI_Express pair (no 50ohm resistor to GND needed)
41	GND	PWR	Ground pin.
42	CPUK8GC_L0	OUT	Complementary signal of low-power differential push-pull AMD K8 "Greyhound" clock
43	CPUK8GT_L0	OUT	True signal of low-power differential push-pull AMD K8 "Greyhound" clock
44	CPUK8GC_L1	OUT	Complementary signal of low-power differential push-pull AMD K8 "Greyhound" clock
45	CPUK8GT_L1	OUT	True signal of low-power differential push-pull AMD K8 "Greyhound" clock
46	GND	PWR	Ground pin.
47	VDDCPU	PWR	Supply for CPU clocks, 3.3V nominal
48	CPUK8GC_L2	OUT	Complementary signal of low-power differential push-pull AMD K8 "Greyhound" clock
49	CPUK8GT_L2	OUT	True signal of low-power differential push-pull AMD K8 "Greyhound" clock
50	CPUK8GC_L3	OUT	Complementary signal of low-power differential push-pull AMD K8 "Greyhound" clock
51	CPUK8GT_L3	OUT	True signal of low-power differential push-pull AMD K8 "Greyhound" clock
52	CPUK8GC_L4	OUT	Complementary signal of low-power differential push-pull AMD K8 "Greyhound" clock
53	CPUK8GT_L4	OUT	True signal of low-power differential push-pull AMD K8 "Greyhound" clock
54	GND	PWR	Ground pin.
55	VDDCPU	PWR	Supply for CPU clocks, 3.3V nominal
56	CPUK8GC_L5	OUT	Complementary signal of low-power differential push-pull AMD K8 "Greyhound" clock
57	CPUK8GT_L5	OUT	True signal of low-power differential push-pull AMD K8 "Greyhound" clock
58	CPUK8GC_L6	OUT	Complementary signal of low-power differential push-pull AMD K8 "Greyhound" clock
59	CPUK8GT_L6	OUT	True signal of low-power differential push-pull AMD K8 "Greyhound" clock
60	SPREAD_EN	IN	Asynchronous, active high input to enable spread spectrum functionality.
61	GND25MHz	PWR	Ground pin for the 25Mhz outputs
62	25MHz_1_2x	OUT	25MHz clock output, 3.3V. Default 2 load drive
63	FS0/25MHz_0_2x	I/O	Frequency select latch input pin / Fixed 25MHz 3.3V clock output. Default 2 load drive
64	VDD25MHz	PWR	Power supply for 25MHz clocks, 3.3V nominal.



### **General Description**

The ICS932S825 is a main clock synthesizer chip that all clocks required by Serverworks HT2400-based servers. An SMBus interface allows full control of the device.

### **Block Diagram**



#### Single-ended Terminations (All Single-Ended Outputs)

Single-ended	Number of	Series Resistor for Proper Termination
<b>Output Strength</b>	Loads on Board	Zo = 50 ohms
1 Load	1	33
2 Load	1	39
(Default)	2	22

#### **Differential Terminations**

Differential	Number of	Series Resistor for Proper Termination
Output	Loads on Board	Zo = 50 ohms
CPUK8Gx	1	33
PCIe_Lx	1	33

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**Frequency Selection Table** 

Byte 0									
Bit 4 SS_EN	Bit 3 FS3	Bit2 FS2	Bit1 FS1	Bit0 FS0	CPU (MHz)	SRC (MHz)	PCI (MHz)	Spread %	OverClock Amount
0	0	0	0	0	Hi-Z	Hi-Z	Hi-Z	N/A	N/A
0	0	0	0	1	X/4	X/8	x/24	N/A	N/A
0	0	0	1	0	180.00	90.00	30.00	0	0.90
0	0	0	1	1	220.00	110.00	36.67	0	1.10
0	0	1	0	0	100.00	100.00	33.33	0	1.00
0	0	1	0	1	133.33	100.00	33.33	0	1.00
0	0	1	1	0			Reserved		
0	0	1	1	1	200.00	100.00	33.33	0	1.00
0	1	0	0	0	184.00	92.00	30.67	0	0.92
0	1	0	0	1	188.00	94.00	31.33	0	0.94
0	1	0	1	0	192.00	96.00	32.00	0	0.96
0	1	0	1	1	196.00	98.00	32.67	0	0.98
0	1	1	0	0	204.00	102.00	34.00	0	1.02
0	1	1	0	1	208.00	104.00	34.67	0	1.04
0	1	1	1	0	212.00	106.00	35.33	0	1.06
0	1	1	1	1	216.00	108.00	36.00	0	1.08
1	0	0	0	0	Hi-Z	Hi-Z	Hi-Z	N/A	N/A
1	0	0	0	1	X/4	X/8	x/24	N/A	N/A
1	0	0	1	0	180.00	90.00	30.00	-0.5%	1.00
1	0	0	1	1	220.00	110.00	36.67	-0.5%	1.00
1	0	1	0	0	100.00	100.00	33.33	-0.5%	1.00
1	0	1	0	1	133.33	100.00	33.33	-0.5%	1.00
1	0	1	1	0			Reserved		
1	0	1	1	1	200.00	100.00	33.33	-0.5%	1.00
1	1	0	0	0	184.00	92.00	30.67	-0.5%	0.92
1	1	0	0	1	188.00	94.00	31.33	-0.5%	0.94
1	1	0	1	0	192.00	96.00	32.00	-0.5%	0.96
1	1	0	1	1	196.00	98.00	32.67	-0.5%	0.98
1	1	1	0	0	204.00	102.00	34.00	-0.5%	1.02
1	1	1	0	1	208.00	104.00	34.67	-0.5%	1.04
1	1	1	1	0	212.00	106.00	35.33	-0.5%	1.06
1	1	1	1	1	216.00	108.00	36.00	-0.5%	1.08

### **CPU Divider Ratios**

	Divider (3:2)										
	Bit	00		01		10		11	MSB		
(1:0)	00	0000	2	0100	4	1000	8	1100	16		
	01	0001	3	0101	6	1001	12	1101	24		
ide	10	0010	5	0110	10	1010	20	1110	40		
Divider	11	0011	15	0111	30	1011	60	1111	120		
_	LSB	Address	Div	Address	Div	Address	Div	Address	Div		

#### **PCI Divider Ratios**

		Divider (3:2)										
	Bit	00		01		10		11	MSB			
(1:0)	00	0000	4	0100	8	1000	16	1100	32			
	01	0001	3	0101	6	1001	12	1101	24			
Divider	10	0010	5	0110	10	1010	20	1110	40			
<u>&gt;i</u>	11	0011	15	0111	30	1011	60	1111	120			
_	LSB	Address	Div	Address	Div	Address	Div	Address	Div			

### **SRC Divider Ratios**

		Divider (3:2)										
(	Bit	00		01		10		11	MSB			
(1:0)	00	0000	2	0100	4	1000	8	1100	16			
	01	0001	3	0101	6	1001	12	1101	24			
ide	10	0010	5	0110	10	1010	20	1110	40			
Divider	11	0011	7	0111	14	1011	28	1111	56			
	LSB	Address	Div	Address	Div	Address	Div	Address	Div			



**Absolute Maximum Ratings** 

Parameter	Symbol	Min	Max	Units	Notes
3.3V Core Supply Voltage	VDDA		GND + 4.5V	V	1
3.3V Logic Input Supply Voltage	VDD		GND +4.5V	٧	1
Storage Temperature	Ts	-50	150	°C	
Ambient Operating Temp	Tambient	0	70	°C	
Input ESD protection human body model	ESD prot	2000		V	1

<sup>&</sup>lt;sup>1</sup>Operation at these extremes is neither implied nor guaranteed

### **Electrical Characteristics - Input/Supply/Common Output Parameters**

 $T_A = 0 - 70$ °C; Supply Voltage  $V_{DD} = 3.3 \text{ V +/-5}\%$ 

PARAMETER	SYMBOL	Conditions	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage	$V_{IH}$		2		$V_{DD} + 0.3$	V	1
Input Low Voltage	V <sub>IL</sub>		V <sub>SS</sub> - 0.3		0.8	V	1
Input High Current	I <sub>IH</sub>	$V_{IN} = V_{DD}$	-5		5	uA	1
Input Low Current	I <sub>IL1</sub>	V <sub>IN</sub> = 0 V; Inputs with no pull-up resistors	-5			uA	1
mpat Low Ourrent	I <sub>IL2</sub>	$V_{IN} = 0 \text{ V}$ ; Inputs with pull-up resistors	-200			uA	1
Operating Current	$I_{DD3.3OP}$	all outputs driven			250	mA	
Powerdown Current	I <sub>DD3.3PD</sub>	all diff pairs Low/Low			15	mA	
Input Frequency <sup>3</sup>	Fi	$V_{DD} = 3.3 \text{ V}$		14.318		MHz	3
Pin Inductance <sup>1</sup>	$L_{pin}$				7	nΗ	1
	C <sub>IN</sub>	Logic Inputs			5	pF	1
Input Capacitance <sup>1</sup>	$C_OUT$	Output pin capacitance			6	pF	1
	$C_{INX}$	X1 & X2 pins			5	pF	1
Clk Stabilization <sup>1,2</sup>	$T_{STAB}$	From V <sub>DD</sub> Power-Up or de-assertion of PD# to 1st clock			3	ms	1,2
Modulation Frequency		Triangular Modulation	30		33	kHz	1
SMBus Voltage	$V_{DD}$		2.7		5.5	V	1
Low-level Output Voltage	$V_{OL}$	@ I <sub>PULLUP</sub>			0.4	V	1
Current sinking at	1		4			mA	1
$V_{OL} = 0.4 \text{ V}$	I <sub>PULLUP</sub>		7			шА	!
SCLK/SDATA	$T_{Rl2C}$	(Max VIL - 0.15) to			1000	ns	1
Clock/Data Rise Time <sup>3</sup>	I RI2C	(Min VIH + 0.15)			1000	113	
SCLK/SDATA	$T_{FI2C}$	(Min VIH + 0.15) to			300	ns	1
Clock/Data Fall Time <sup>3</sup>	' FI2C	(Max VIL - 0.15)			300	113	!

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>2</sup>See timing diagrams for timing requirements.

<sup>&</sup>lt;sup>3</sup> Input frequency should be measured at the REFOUT pin and tuned to ideal 14.31818MHz to meet ppm frequency accuracy on PLL outputs.



### **AC Electrical Characteristics - Low Power Differential PCIe Outputs**

 $T_A = 0 - 70^{\circ}C$ ;  $V_{DD} = 3.3 \text{ V +/-5\%}$ ;  $C_L = 2pF$ ,  $R_S = 33.2\Omega$ 

$T_A = 0.70 \text{ G}, V_{DD} = 3.3 \text{ V} + 7.3 \text{ G}, G_L = 2 \text{pr}, H_S = 33.2 \text{ M}$									
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES		
Rising Edge Slew Rate	t <sub>SLR</sub>	Differential Measurement	0.5		2	V/ns	1,2		
Falling Edge Slew Rate	t <sub>FLR</sub>	Differential Measurement	0.5		2	V/ns	1,2		
Slew Rate Variation	t <sub>SLVAR</sub>	Single-ended Measurement			20	%	1		
Maximum Output Voltage	$V_{HIGH}$	Includes overshoot			1150	mV	1		
Minimum Output Voltage	$V_{LOW}$	Includes undershoot	-300			mV	1		
Differential Voltage Swing	$V_{SWING}$	Differential Measurement	400			mV	1		
Crossing Point Voltage	$V_{XABS}$	Single-ended Measurement	300		550	mV	1,3,4		
Crossing Point Variation	$V_{XABSVAR}$	Single-ended Measurement			140	mV	1,3,5		
Duty Cycle	D <sub>CYC</sub>	Differential Measurement	45		55	%	1		
PCIe Jitter - Cycle to Cycle	PCleJ <sub>C2C</sub>	Differential Measurement			125	ps	1		
PCIe[6:0] Skew	PCIe <sub>SKEW</sub>	Differential Measurement			250	ps	1		

#### **Notes on Electrical Characteristics:**

#### **PCle Phase Jitter Impact**

- Olo I Habb Chitch III	.pas.						
Parameter		Conditions	Min	Typical	Max	Units	Notes
Output phase jitter impact – PCIe* Gen1	$\theta_{PCle1}$	(including PLL BW 1.5-22 MHz, z = 0.54, Td=10 ns, Ftrk=1.5 MHz )	0		108	ps	1,2,3,4
Output phase jitter impact - PCIe Gen2	$\theta_{PCle2}$	(including PLL BW5-16 MHz, 8 – 16 MHz, z = 0.54, Td=10 ns)	0		3.1	ps RMS	1,2,3,4

#### NOTES:

- 1. Post processed evaluation through Intel supplied Matlab scripts.
- 2. PCle\* Gen2 filter characteristics are subject to final ratification by PC ISIG. Please check the PCl\* SIG for the latest specification.
- 3. These jitter numbers are defined for a BER of 1E-12. Measured numbers at a smaller sample size have to be extrapolated to this BER target.
- 4. Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>2</sup> Slew rate measured through Vswing centered around differential zero

<sup>&</sup>lt;sup>3</sup> Vxabs is defined as the voltage where CLK = CLK#

<sup>&</sup>lt;sup>4</sup> Only applies to the differential rising edge (CLK rising and CLK# falling)

<sup>&</sup>lt;sup>5</sup> Defined as the total variation of all crossing voltages of CLK rising and CLK# falling.

<sup>&</sup>lt;sup>6</sup> All Long Term Accuracy and Clock Period specifications are guaranteed assuming that REFOUT is at 14.31818MHz



### **AC Electrical Characteristics - Low Power Differential CPU Outputs**

 $T_A = 0 - 70$ °C;  $V_{DD} = 3.3 \text{ V +/-5\%}$ ;  $C_L = AMD64 \text{ Processor Test Load}$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Crossing Point Variation	$\Delta V_{CROSS}$	Single-ended Measurement			140	mV	1
Frequency	f	ŭ.	198.8		200	MHz	2
Long Term Accuracy	ppm		-300		300	ppm	3
Rising Edge Slew Rate	t <sub>SLR</sub>	Differential Measurement	0.5		10	V/ns	4,5
Falling Edge Slew Rate	$t_{FLR}$	Differential Measurement	0.5		10	V/ns	4,5
CPU Jitter - Cycle to Cycle	CPUJ <sub>C2C</sub>	Differential Measurement			150	ps	6
CPU Jitter - Accumulated	CPUJ <sub>ACC</sub>	Over a 10 uS period	-1		1	ns	7
Maximum Output Voltage	$V_{HIGH}$	Includes overshoot, single-ended measurement			1150	mV	1
Minimum Output Voltage	$V_{LOW}$	Includes undershoot, single-ended measurement	-300			mV	1
Differential Voltage Swing Peak-to-Peak	$V_{DPK-PK}$	Differential Measurement	400		2400	mV	8
Differential Voltage	$V_D$	Differential Measurement	200		1200	mV	9
Change in V <sub>D</sub> DC cycle-to- cycle	$\Delta V_D$	Single-ended Measurement	-75		75	mV	10
Duty Cycle	D <sub>CYC</sub>	Differential Measurement	45		55	%	11
CPU[6:0] Skew	CPU <sub>SKEW10</sub>	Differential Measurement			250	ps	

Notes on Electrical Characteristics (Guaranteed by design and characterization, not 100% tested in production):

<sup>&</sup>lt;sup>1</sup>Single-ended measurement at crossing point. Value is max-min over all time. DC value of common mode is not important due to the blocking cap.

<sup>&</sup>lt;sup>2</sup> Minimum frequency results from 0.5% down spread.

<sup>&</sup>lt;sup>3</sup> Measured with spread spectrum off.

<sup>&</sup>lt;sup>4</sup> This parameter is intended to give guidance for simulation.

<sup>&</sup>lt;sup>5</sup> Differential measurement through the range of +/-100mV

<sup>&</sup>lt;sup>6</sup> Between any two adjacent cycles.

<sup>&</sup>lt;sup>7</sup> Accumulated over a 10 uS time periode, measured with JIT2 TIE at 50ps interval.

<sup>&</sup>lt;sup>8</sup> V<sub>DPK-PK</sub> is the overall magnitude of the differential signal.

 $<sup>^{9}</sup>$  V<sub>DMIN</sub> is the amplitude of the ring-back differential measurement, guaranteed by design, that ring-back will not cross 0V V<sub>D</sub>. V<sub>DMAX</sub> is the largest amplitude allowed.

 $<sup>^{10}</sup>$  The difference in magnitude of two adjacent  $V_{DDC}$  measurements.  $V_{DDC}$  is the stable post overshoot and ring-back part

<sup>11</sup> Defined as tHIGH/tCYCLE



#### **Electrical Characteristics - 33 MHz PCICLK, 25MHz Outputs**

 $T_A = 0 - 70^{\circ}\text{C}$ ; VDD=3.3V +/-5%;  $C_L = 5 \text{ pF}$  (unless otherwise specified)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	Notes
PCI Long Accuracy	ppm	see Tperiod min-max values	-300		300	ppm	1,2
PCI Clock period	$T_{period}$	33.33MHz output nominal	29.9910		30.0090	ns	2
FOI Clock period	' period	33.33MHz output spread	29.9910		30.1598	ns	2
25MHz Long Accuracy	ppm	see Tperiod min-max values	-50		50	ns	2
25MHz Clock period	$T_{period}$	25MHz output nominal		40		ns	2
Output High Voltage	$V_{OH}$	$I_{OH} = -1 \text{ mA}$	2.4			V	1
Output Low Voltage	$V_{OL}$	$I_{OL} = 1 \text{ mA}$			0.55	V	1
Output High Current	1	V <sub>OH</sub> @MIN = 1.0 V	-33			mA	1
Output High Current	I <sub>ОН</sub>	V <sub>OH</sub> @ MAX = 3.135 V			-33	mA	1
Output Low Current	1	V <sub>OL</sub> @ MIN = 1.95 V	30			mA	1
Output Low Current	I <sub>OL</sub>	$V_{OL}$ @ MAX = 0.4 V			38	mA	1
Edge Rate	$\delta V/\delta t$	Rising edge rate	1		4	V/ns	1
Edge Rate	$\delta V/\delta t$	Falling edge rate	1		4	V/ns	1
Duty Cycle	d <sub>t1</sub>	$V_{T} = 1.5 \text{ V}$	45		55	%	1
PCI Skew	t <sub>sk1</sub>	$V_{T} = 1.5 \text{ V}$			250	ps	1
25MHz Skew	t <sub>sk1</sub>	$V_{T} = 1.5 \text{ V}$			250	ps	1
Jitter, Cycle to cycle	t <sub>jcyc-cyc</sub>	V <sub>T</sub> = 1.5 V			250	ps	1

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

#### **Electrical Characteristics - 48MHz**

 $T_{A}$  = 0 - 70°C;  $V_{DD}$  = 3.3 V +/-5%;  $C_{L}$  = 5 pF (unless otherwise specified)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	Notes
Long Accuracy	ppm	see Tperiod min-max values	-100		100	ppm	1,2
Clock period	$T_{period}$	48.00MHz output nominal	20.8257		20.8340	ns	2
Output High Voltage	$V_{OH}$	$I_{OH} = -1 \text{ mA}$	2.4			V	1
Output Low Voltage	$V_{OL}$	$I_{OL} = 1 \text{ mA}$			0.55	V	1
Output High Current	I.	V <sub>OH</sub> @ MIN = 1.0 V	-33			mA	1
Output High Current	I <sub>OH</sub>	$V_{OH}$ @ MAX = 3.135 V			-33	mA	1
Output Low Current	1.	V <sub>OL</sub> @MIN = 1.95 V	30			mA	1
Output Low Current	I <sub>OL</sub>	$V_{OL} @ MAX = 0.4 V$			38	mA	1
Edge Rate	$\delta V/\delta t$	Rising edge rate	1		2	V/ns	1
Edge Rate	$\delta V/\delta t$	Falling edge rate	1		2	V/ns	1
Duty Cycle	d <sub>t1</sub>	$V_{T} = 1.5 \text{ V}$	45		55	%	1
Group Skew	t <sub>sk1</sub>	$V_{T} = 1.5 \text{ V}$			250	ps	1
Jitter, Cycle to cycle	t <sub>icyc-cyc</sub>	$V_{T} = 1.5 \text{ V}$			250	ps	1

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>2</sup> All Long Term Accuracy and Clock Period specifications are guaranteed assuming that REF is at 14.31818MHz

<sup>&</sup>lt;sup>2</sup> All Long Term Accuracy and Clock Period specifications are guaranteed assuming that REF is at 14.31818MHz



#### **Electrical Characteristics - REF-14.318MHz**

 $T_A = 0 - 70$ °C;  $V_{DD} = 3.3 \text{ V +/-5\%}$ ;  $C_L = 5 \text{ pF}$  (unless otherwise specified)

		, ,					
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	Notes
Long Accuracy	ppm	see Tperiod min-max values	-300		300	ppm	1
Clock period	$T_{period}$	14.318MHz output nominal	69.8270		69.8550	ns	2
Output High Voltage	$V_{OH}$	I <sub>OH</sub> = -1 mA	2.4			V	1
Output Low Voltage	$V_{OL}$	I <sub>OL</sub> = 1 mA			0.4	V	1
Output High Current	I <sub>OH</sub>	V <sub>OH</sub> @MIN = 1.0 V, V <sub>OH</sub> @MAX = 3.135 V	-29		-23	mA	1
Output Low Current	l <sub>OL</sub>	$V_{OL}$ @MIN = 1.95 V, $V_{OL}$ @MAX = 0.4 V	29		27	mA	1
Edge Rate	$\delta V/\delta t$	Rising edge rate	1		2	V/ns	1
Edge Rate	$\delta V/\delta t$	Falling edge rate	1		2	V/ns	1
Skew	t <sub>sk1</sub>	$V_{T} = 1.5 \text{ V}$			500	ps	1
Duty Cycle	d <sub>t1</sub>	$V_{T} = 1.5 \text{ V}$	45		55	%	1
Jitter, Cycle to cycle	t <sub>jcyc-cyc</sub>	V <sub>T</sub> = 1.5 V			1000	ps	1

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>2</sup> All Long Term Accuracy and Clock Period specifications are guaranteed assuming that REF is at 14.31818MHz



### **General SMBus serial interface information**

#### **How to Write:**

- · Controller (host) sends a start bit.
- Controller (host) sends the write address D2<sub>(h)</sub>
- ICS clock will acknowledge
- Controller (host) sends the begining byte location = N
- ICS clock will acknowledge
- Controller (host) sends the data byte count = X
- ICS clock will acknowledge
- Controller (host) starts sending Byte N through Byte N + X -1
- ICS clock will acknowledge each byte one at a time
- Controller (host) sends a Stop bit

Ind	ex Block W	/rit	e Operation
Cor	ntroller (Host)		ICS (Slave/Receiver)
Т	starT bit		
Slav	e Address D2 <sub>(h)</sub>		
WR	WRite		
			ACK
Begi	nning Byte = N		
			ACK
Data	Byte Count = X		
			ACK
Begir	ning Byte N		
			ACK
	$\Diamond$	′te	
	<b>\rightarrow</b>	X Byte	<b>\Q</b>
	<b>\rightarrow</b>	×	$\diamond$
			<b>\Q</b>
Byte	e N + X - 1		
			ACK
Р	stoP bit		

#### **How to Read:**

- Controller (host) will send start bit.
- Controller (host) sends the write address D2<sub>(n)</sub>
- ICS clock will acknowledge
- Controller (host) sends the begining byte location = N
- ICS clock will acknowledge
- Controller (host) will send a separate start bit.
- Controller (host) sends the read address D3 (h)
- ICS clock will acknowledge
- ICS clock will send the data byte count = X
- ICS clock sends Byte N + X -1
- ICS clock sends Byte 0 through byte X (if X<sub>(h)</sub> was written to byte 8).
- · Controller (host) will need to acknowledge each byte
- Controllor (host) will send a not acknowledge bit
- · Controller (host) will send a stop bit

Ind	ex Block Rea	ad	Operation		
Con	troller (Host)	IC	S (Slave/Receiver)		
Т	starT bit				
Slave	e Address D2 <sub>(h)</sub>				
WR	WRite				
	•	ACK			
Begi	nning Byte = N				
			ACK		
RT	Repeat starT				
Slave	e Address D3 <sub>(h)</sub>				
RD	ReaD				
			ACK		
		Data Byte Count = X			
	ACK				
			Beginning Byte N		
	ACK				
		X Byte	○		
	<b>\rightarrow</b>	B	<b>\Q</b>		
	<b>\rightarrow</b>	×	<b>\Q</b>		
0					
			Byte N + X - 1		
N	Not acknowledge				
Р	stoP bit				

1276F—12/02/08

SMBus Table: Frequency Select and Spread Control Register

Byt	te 0	Pin #	Name	Control Function	Type	0	1	PWD
Bit 7			Reserved	Reserved	RW	Reserved	Reserved	0
Bit 6		-	Reserved	Reserved	RW	Reserved	Reserved	0
Bit 5			Reserved	Reserved	RW	Reserved	Reserved	0
Bit 4		-	SS_EN	Spread Spectrum Enable	RW		Latched	
Bit 3		-	FS3	Freq Select Bit 3	RW	See CPU Frequ	ioney Soloet	0
Bit 2		-	FS2	Freq Select Bit 2	RW	Tab	•	Latched
Bit 1		-	FS1	Freq Select Bit 1	RW			Latched
Bit 0		-	FS0	Freq Select Bit 0	RW			Latched

**SMBus Table: Output Control Register** 

		at comact magnet					
Byte	e 1 Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7	6	REF2	Output Enable	RW	Hi-Z	Enable	1
Bit 6	5	REF1	Output Enable	RW	Hi-Z	Enable	1
Bit 5	4	REF0_RUN	Output Enable	RW	Disable (Low)	Enable	1
Bit 4	17	PCICLK1	Output Enable	RW	Disable (Low)	Enable	1
Bit 3	16	PCICLK0	Output Enable	RW	Disable (Low)	Enable	1
Bit 2	-	Reserved	Reserved	RW	Reserved	Reserved	1
Bit 1	10	48MHz_1	Output Enable	RW	Disable (Low)	Enable	1
Bit 0	9	48MHz 0	Output Enable	RW	Disable (Low)	Enable	1

**SMBus Table: Output Control Register** 

Byt	te 2	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7			Reserved	Reserved	RW	Reserved	Reserved	0
Bit 6	59/	/58	CPUK8G_L(6)	RI		Disable	Enable	1
Bit 5	57/	/56	CPUK8G_L(5)	Output Enable	RW	Disable	Enable	1
Bit 4	53/	/52	CPUK8G_L(4)	4) When Disabled RW Disable		Enable	1	
Bit 3	51/	/50	CPUK8G_L(3)		RW	Disable	Enable	1
Bit 2	47/	/46	CPUK8G_L(2)	$CPUK8GT_L = 0$ CPUK8GC L = 0	RW	Disable	Enable	1
Bit 1	45/	/44	CPUK8G_L(1)	CFUROGC_L = U	RW	Disable	Enable	1
Bit 0	43/	/42	CPUK8G_L(0)		RW	Disable	Enable	1

**SMBus Table: Output Control Register** 

CIVIDA	o rabic. O	Juipu	t Control negist	G1				
Byt	te 3 Pi	in #	Name	Control Function	Type	0	1	PWD
Bit 7	-		Reserved	Reserved	RW	Reserved	Reserved	0
Bit 6	40/39	)	PCIe_L6		RW	Disable	Enable	1
Bit 5	38/37	'	PCIe_L5	Output Enable	RW	Disable	Enable	1
Bit 4	33/34		PCIe_L4	When Disabled	RW	Disable	Enable	1
Bit 3	31/32	)	PCIe_L3	PCIeT_L = 0	RW	Disable	Enable	1
Bit 2	29/30	)	PCIe_L2	PCIeT_L = 0 PCIeC_L = 0	RW	Disable	Enable	1
Bit 1	25/26	;	PCle_L1	POIeC_L = 0	RW	Disable	Enable	1
Bit 0	23/24		PCIe_L0		RW	Disable	Enable	1

**SMBus Table: Drive Strength Control Register** 

Byt	te 4 Pin #	Name	Control Function	Type	0	1	PWD
Bit 7	6	REF2	Drive Strength Select	RW	1 Load	2 Loads	1
Bit 6	5	REF1	Drive Strength Select	RW	1 Load	2 Loads	1
Bit 5	4	REF0_RUN	Drive Strength Select	RW	1 Load	2 Loads	1
Bit 4	17	PCICLK1	Drive Strength Select	RW	1 Load	2 Loads	1
Bit 3	16	PCICLK0	Drive Strength Select	RW	1 Load	2 Loads	1
Bit 2	11	48MHz_2	Drive Strength Select	RW	1 Load	2 Loads	1
Bit 1	10	48MHz_1	Drive Strength Select	RW	1 Load	2 Loads	1
Bit 0	9	48MHz_0	Drive Strength Select	RW	1 Load	2 Loads	1

**SMBus Table: Drive Strength Control Register** 

Byte	e 5 Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7	62	25MHz_1	Output Enable	RW	Low	Enable	1
Bit 6	63	25MHz_0	Output Enable	RW	Hi-Z	Enable	1
Bit 5	62	25MHz_1	Drive Strength Select	RW	1 Load	2 Loads	1
Bit 4	63	25MHz_0	Drive Strength Select	RW	1 Load	2 Loads	1
Bit 3	-	Reserved	Reserved	RW	Reserved	Reserved	0
Bit 2	-	VDIFF2	VDIFF MSB	RW			1
Bit 1	-	VDIFF1	VDIFF Select Bit 0	RW	See VDIFF S	elect Table	0
Bit 0	-	VDIFF0	VDIFF LSB	RW			1

**SMBus Table: Device ID Register** 

Byt	te 6	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7	-	-	DevID 7	Device ID MSB	R	-	ı	0
Bit 6	-		DevID 6	Device ID 6	R	-	ı	0
Bit 5	_	-	DevID 5	Device ID 5	R	-	ı	1
Bit 4	_	-	DevID 4	Device ID4	R	-	-	0
Bit 3	-	-	DevID 3	Device ID3	R	-	-	0
Bit 2	-	-	DevID 2	Device ID2	R	-	-	1
Bit 1	-		DevID 1	Device ID1	R	-	-	0
Bit 0	-	-	DevID 0	Device ID LSB	R	-	-	1

**SMBus Table: Vendor ID Register** 

<u> </u>	indus rubic. Vendor ib riegister											
Byte	e 7 Pin #	Name	Control Function	Type	0	1	PWD					
Bit 7	-	RID3		R	-	-	0					
Bit 6	-	RID2	Revision ID	R	-	-	0					
Bit 5	-	RID1	nevision iD	R	-	-	0					
Bit 4	-	RID0		R	-	-	1					
Bit 3	-	VID3		R	-	-	0					
Bit 2	-	VID2	VENDOR ID	R	-	-	0					
Bit 1	-	VID1	(0001 = ICS)	R	-	-	0					
Bit 0	-	VID0		R	-	-	1					

**SMBus Table: Byte Count Register** 

Byte	e 8 Pin #	Name	Control Function	Type	0	1	PWD		
Bit 7	-	BC7		RW			0		
Bit 6	-	BC6		RW			0		
Bit 5	-	BC5		RW	Writing to this	register will	0		
Bit 4	-	BC4	Byte Count Programming	RW	configure how	many bytes	0		
Bit 3	-	BC3	b(7:0)	RW	will be read bad	ck, default is	1		
Bit 2	-	BC2		RW	9 byt	es.	0		
Bit 1	-	BC1		RW			0		
Bit 0	-	BC0		RW			1		

**SMBus Table: Reserved Register** 

Byt	te 9	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7			Reserved	Reserved	RW	Reserved	Reserved	0
Bit 6			Reserved	Reserved	RW	Reserved	Reserved	0
Bit 5			Reserved	Reserved	RW	Reserved	Reserved	0
Bit 4			Reserved	Reserved	RW	Reserved	Reserved	0
Bit 3			Reserved	Reserved	RW	Reserved	Reserved	0
Bit 2			Reserved	Reserved	RW	Reserved	Reserved	0
Bit 1		-	Reserved	Reserved	RW	Reserved	Reserved	0
Bit 0		-	Reserved	Reserved	RW	Reserved	Reserved	0

SMBus Table: M/N Programming Enable

Byt	e 10	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7		-	M/N_EN	CPU PLL M/N Programming Enable	RW	Disable	Enable	0
Bit 6		-	Reserved	Reserved	RW	-	1	0
Bit 5		-	Reserved	Reserved	RW	-	1	0
Bit 4		-	Reserved	Reserved	RW	-	-	0
Bit 3		-	Reserved	Reserved	RW	-	-	0
Bit 2		-	Reserved	Reserved	RW	-	-	0
Bit 1		-	Reserved	Reserved	RW	-	-	0
Bit 0		-	Reserved	Reserved	RW	-	1	0



### Bytes 11:14 are Reserved Registers

SMBus Table: CPU Frequency Control Register

Byte	e 15	Pin #	Name	Control Function	Type	0	1	PWD
Bit 7		-	N Div8	N Divider Prog bit 8	RW	The desimal re	nraa antatian	Χ
Bit 6		-	N Div9	N Divider Prog bit 9	RW	The decimal representation of M and N Divier in Byte 11		Χ
Bit 5		-	M Div5		RW	and 12 will co	,	Χ
Bit 4		-	M Div4		RW	CPU VCO f	•	Χ
Bit 3		-	M Div3	M Divider Programming	RW	Default at power	•	Χ
Bit 2		-	M Div2	bit (5:0)	RW	in or Byte 0 Ro		Χ
Bit 1		-	M Div1		RW	Frequency = [NDiv(9:0)+8] /		Χ
Bit 0		-	M Div0		RW		[101010 (3.0)+2]	Χ

**SMBus Table: CPU Frequency Control Register** 

Byte	e 16	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7		-	N Div7		RW	The desimal re	proportation	Χ
Bit 6		-	N Div6		RW	The decimal representation of M and N Divier in Byte 11		Х
Bit 5		-	N Div5	ND: : L D	RW	and 12 will co	•	Х
Bit 4		-	N Div4	N Divider Programming Byte12 bit(7:0) and Byte11	RW	CPU VCO f	•	Х
Bit 3		-	N Div3	bit(7:6)	RW	Default at power	•	Х
Bit 2		-	N Div2	Sin(7.10)	RW	in or Byte 0 Ro		Х
Bit 1		-	N Div1		RW	Frequency = [NDiv(9:0)+8] /		Х
Bit 0		-	N Div0		RW	[[NDIV(8.0)+6] /	[[VIDIV(3.0)+2]	Х

SMBus Table: CPU Spread Spectrum Control Register

Byte	e 17	Pin #	Name	Control Function	Type	0	1	PWD
Bit 7		-	SSP7		RW			Χ
Bit 6		-	SSP6		RW			Χ
Bit 5		-	SSP5		RW	These Spread S	Spectrum bits	Χ
Bit 4			SSP4	Spread Spectrum	RW	in Byte 13 and 14 will		Χ
Bit 3		-	SSP3	Programming bit(7:0)	RW	program the	e spread	Χ
Bit 2		-	SSP2		RW	pecentage	of CPU	Χ
Bit 1		-	SSP1		RW			Χ
Bit 0		-	SSP0		RW			X

SMBus Table: CPU Spread Spectrum Control Register

Byte	e 18	Pin#	Name	Control Function	Type	0	1	PWD
Bit 7	•	•	Reserved	Reserved	R	-	-	0
Bit 6	-		SSP14		RW			Χ
Bit 5	-		SSP13		RW	Thosa Carood C	Spootwym bito	Χ
Bit 4	-	•	SSP12	Caread Caastrum	RW	RW These Spread S	'	Χ
Bit 3	-	•	SSP11	Spread Spectrum	RW in Byte 13 and 1 program the spi		Χ	
Bit 2	-	•	SSP10	Programming bit(14:8)	RW	. •	•	Χ
Bit 1	-		SSP9		RW	pecentage of CPU		Χ
Bit 0			SSP8		RW			Χ

**SMBus Table: Programmable Output Divider Register** 

Byte	e 19 Pi	n#	Name	Control Function	Туре	0	1	PWD
Bit 7	•		CPUDiv3		RW			Χ
Bit 6	-		CPUDiv2	CPU Divider Ratio	RW	See CPU Divider Ratios		Χ
Bit 5	•		CPUDiv1	Programming Bits	RW	Tab	le	Χ
Bit 4	•		CPUDiv0		RW			Χ
Bit 3	-		Reserved	Reserved	R	-	-	0
Bit 2	-		Reserved	Reserved	R	-	-	0
Bit 1	-		Reserved	Reserved	R	-	-	0
Bit 0	-		Reserved	Reserved	R	-	-	0

SMBus Table: Programmable Output Divider Register

Byte	e 20 Pin	# Name	Control Function	Туре	0	1	PWD
Bit 7	1	33MHzDiv3		RW			Χ
Bit 6	1	33MHzDiv2	33MHz Divider Ratio	RW	33MHz Divider Ratio Table		Χ
Bit 5	1	33MHzDiv1	Programming Bits	RW			Χ
Bit 4	1	33MHzDiv0		RW			Χ
Bit 3	-	SRC_Div3		RW			Χ
Bit 2	-	SRC_Div2	SRC_ Divider Ratio	RW	SRC Divider Ratio Table		Χ
Bit 1	-	SRC_Div1	Programming Bits	RW			Χ
Bit 0	-	SRC_Div0		RW			Χ

SMBusTable: Reserved Regsiter

Byte 21 is reserved do not write this register!



## Shared Pin Operation - Input/Output Pins

The I/O pins designated by (input/output) on the ICS932S825 serve as dual signal functions to the device. During initial power-up, they act as input pins. The logic level (voltage) that is present on these pins at this time is read and stored into a 5-bit internal data latch. At the end of Power-On reset, (see AC characteristics for timing values), the device changes the mode of operations for these pins to an output function. In this mode the pins produce the specified buffered clocks to external loads.

To program (load) the internal configuration register for these pins, a resistor is connected to either the VDD (logic 1) power supply or the GND (logic 0) voltage potential. A 10 Kilohm (10K) resistor is used to provide both the solid CMOS programming voltage needed during the power-up programming period and to provide an insignificant load on the output clock during the subsequent operating period.

Figure 1 shows a means of implementing this function when a switch or 2 pin header is used. With no jumper is installed the pin will be pulled high. With the jumper in place the pin will be pulled low. If programmability is not necessary, than only a single resistor is necessary. The programming resistors should be located close to the series termination resistor to minimize the current loop area. It is more important to locate the series termination resistor close to the driver than the programming resistor.

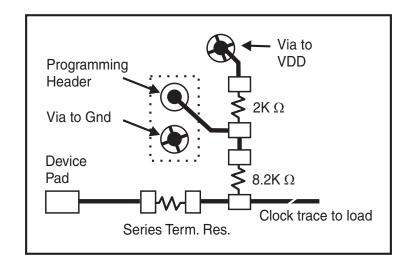
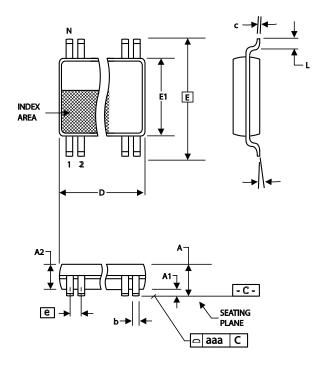


Fig. 1



6.10 mm. Body, 0.50 mm. Pitch TSSOP (240 mil) (20 mil)

	(240 11111)	(20 11111)			
	In Milli	meters	In Inches		
SYMBOL	COMMON DIMENSIONS		COMMON DIMENSIONS		
	MIN	MAX	MIN	MAX	
Α		1.20		.047	
A1	0.05	0.15	.002	.006	
A2	0.80	1.05	.032	.041	
b	0.17	0.27	.007	.011	
С	0.09	0.20	.0035	.008	
D	SEE VARIATIONS SEE VA		SEE VAF	RIATIONS	
Е	8.10 BASIC		0.319 BASIC		
E1	6.00	6.20	.236	.244	
е	0.50 BASIC		0.020 BASIC		
L	0.45	0.75	.018	.030	
N	SEE VARIATIONS		SEE VARIATIONS		
α	0°	8°	0°	8°	
aaa		0.10		.004	

#### **VARIATIONS**

NI	Dr	nm.	D (inch)		
IN	MIN	MAX	MIN	MAX	
64	16.90	17.10	.665	.673	

Reference Doc.: JEDEC Publication 95, MO-153

10-0039

## **Ordering Information**

## 932S825yGLFT

Example:



**Revision History** 

Rev.	Issue Date	Description	Page #
		Updated Electrical Characteristics.	
		2. Going to Preliminary.	
Α	2/28/2007	3. Updated Idd to reflect low power outputs	Various
В	9/11/2007	Updated pin description	2, 3
С	9/12/2007	Updated quantity of PCIEX outputs listed under "Output Features"	1
D	10/25/2007	<ol> <li>Corrected CPU/SRC/PCI PLL control bytes to B(15:18) from B(11:14)</li> <li>Changed pin names to indicate default drive strength. NO silicon changes.</li> <li>Corrected Byte 0 SS_EN and FS3 reference in FS table.</li> <li>Simplified the Terminations Table</li> <li>Release to Final</li> </ol>	1, 2, 3, 4, 5, 16,17
E	12/14/2007	Updated SMBus serial Interface Information	12
F	12/2/2008	Removed ICS prefix from ordering information.	19

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