

R1QGA3636CBG / R1QGA3618CBG / R1QGA3609CBG R1QKA3636CBG / R1QKA3618CBG / R1QKA3609CBG

36-Mbit QDR™II+ SRAM 4-word Burst

Rev. 0.08a 2011.05.23

Description

The R1Q#A3636 is a 1,048,576-word by 36-bit, the R1Q#A3618 is a 2,097,152-word by 18-bit, and the R1Q#A3609 is a 4,194,304-word by 9-bit synchronous quad data rate static RAM fabricated with advanced CMOS technology using full CMOS six-transistor memory cell. It integrates unique synchronous peripheral circuitry and a burst counter. All input registers are controlled by an input clock pair (K and /K) and are latched on the positive edge of K and /K. These products are suitable for applications which require synchronous operation, high speed, low voltage, high density and wide bit configuration. These products are packaged in 165-pin plastic FBGA package.

= G: Read Latency =2.0, w/o ODT # = K: Read Latency =2.0, w/ ODT

Features

- Power Supply
 - 1.8 V for core (V_{DD}) , 1.4 V to V_{DD} for I/O (V_{DDO})
- Clock
 - Fast clock cycle time for high bandwidth
 - Two input clocks (K and /K) for precise DDR timing at clock rising edges only
 - Two output echo clocks (CQ and /CQ) simplify data capture in high-speed systems
 - Clock-stop capability with us restart
- I/O
 - Separate independent read and write data ports with concurrent transactions
 - 100% bus utilization DDR read and write operation
 - HSTL I/O
 - User programmable output impedance
 - DLL circuitry for wide output data valid window and future frequency scaling
 - Data valid pin (QVLD) to indicate valid data on the output
- Function
 - Four-tick burst for reduced address frequency
 - Internally self-timed write control
 - Simple control logic for easy depth expansion
 - JTAG 1149.1 compatible test access port
- Package
 - 165 FBGA package (15 x 17 x 1.4 mm)

Notes: 1. QDR RAMs and Quad Data Rate RAMs comprise a new family of products developed by Cypress Semiconductor, IDT, Samsung, and Renesas Electronics Corp. (QDR Co-Development Team)

- 2. The specifications of this device are subject to change without notice. Please contact your nearest Renesas Electronics Sales Office regarding specifications.
- 3. Refer to

"http://www.renesas.com/products/memory/fast_sram/qdr_sram_root.jsp" for the latest and detailed information.

Ordering Information

Part Number Definition Table

No.	0	1	2	3	4	5	6	7	8	9	10	11	-	12	13	14	15	16
Example	R	1	Q	Α	Α	7	2	3	6	Α	В	G	-	2	0	R	В	0

No.	-	Comments	No.	-	Comments	No.	-	Comments
0-1		Renesas Memory Prefix	4	Α	Vdd = 1.8 V		60	Frequency = 167MHz
	Q2	QDR B2 ^[*1] (L15) ^[*2]		36	Density = 36Mb		50	Frequency = 200MHz
	Q3	QDR II B4 (L15)	5-6	72	Density = 72Mb		40	Frequency = 250MHz
	Q4	DDR 11 B2 (L15)	3 0	44	Density = 144Mb		36	Frequency = 275MHz
		DDR II B4 (L15)		88	Density = 288Mb		33	Frequency = 300MHz
	Q6	DDR B2 S 0 ^[*3] (L15)		09	Data width = 9bit	12-13	30	Frequency = 333MHz
	QA	QDR + B4 L25 ^[*2]	7-8	18	Data width = 18bit		27	Frequency = 375MHz
	QB	DDR II+ B2 L25		36	Data width = 36bit		25	Frequency = 400MHz
		DDR II+ B4 L25		R	1st Generation		22	Frequency = 450MHz
	QD	QDR + B4 L25 w/ODT [*4]		Α	2nd Generation		20	Frequency = 500MHz
		DDR II+ B2 L25 w/ODT		В	3rd Generation		19	Frequency = 533MHz
2-3	QF	DDR II+ B4 L25 w/ODT	9	С	4th Generation		R	Commercial temp.
	QG	QDR 11+ B4 L20		D	5th Generation	14	, r	Ta range = 0°C∼70°C
		DDR 11+ B2 L20		E	6th Generation	17	l 1	Industrial temp.
	QJ	DDR 11+ B4 L20		F	7th Generation		'	Ta range = -40℃~85℃
	QK	QDR II+ B4 L20 w/ODT	10-11		PKG= BGA 15x17 mm			Pb and Tray
	QL	DDR 11+ B2 L20 w/ODT	10 11	BA	PKG= BGA 13x15 mm	15		Pb-free and Tray
	QM	DDR II+ B4 L20 w/ODT				10		Pb and Tape&Reel
	QN	QDR 11+ B2 L20						Pb-free and Tape&Reel
	QP	QDR II+ B2 L20 w/ODT				16	0~9, A~Z	Renesas internal use
						. •	or None	

Note1: [*1] B=Burst length (B2: Burst length=2, B4: Burst length=4)

[*2] L=Read Latency (L15: Read Latency = 1.5 cycle, L20: 2.0 cycle, L25: 2.5 cycle)

[*3] SIO=Separate I/O [*4] ODT=On die termination

Note2: Package Marking Name

Pb parts: Marking Name = Part Number(0-14)
Pb-free parts: Marking Name = Part Number(0-14) + "PB-F" ---- Pb (Example) R1QAA7236ABG-20R parts R1QAA7236ABG-20R PB-F ---- Pb-free parts

Note3: Pb : RoHS Compliance Level = 5/6 Pb-free: RoHS Compliance Level = 6/6

Generation Number Table

Density	Туре	Generation Number *1	Notes
36Mb	II+	С	1, 2
72Mb	II & II+	A	1, 2
144Mb	II & II+	R	1
288Mb	II & II+	R	1

Notes:

1. As of the day when this datasheet was issued.

2. Both "Commercial" and "Industrial" temperatures are supported by "Industrial" temperature version.

Speed Bin Table

								QI	OR II+	/ DDR	II+		QDR II / DDR II			
	act e	st th	cy (e)	_	ni- n	Frequency (max) (MHz)	533	500	450	400	375	333	333	300	250	200
No	Product Type	Burst Length	Latency (Cycle)	ODT	Organi- zation	Cycle Time (min) (ns)	1.875	2.00	2.22	2.50	2.66	3.00	3.00	3.30	4.00	5.00
						Part Number ↓ yy →	-19	-20	-22	-25	-27	-30	-30	-33	-40	-50
17	QDRII+	B4				R1Q A A36 18 C Bv- yy	-19	-20	-22							
18						R1Q A A36 36 C Bv- yy										
20		B2	2.5	9 N		R1Q B A36 18 C Bv- yy	-19	-20	-22							
21	DDRII+		7	_		R1Q B A36 36 C Bv- yy										
23 24		В4				R1Q C A36 18 C Bv- yy	-19	-20	-22							
24						R1Q C A36 36 C Bv- yy										
26 27	QDRII+	B4				R1Q D A36 18 C Bv- yy	-19	-20	-22							
29						R1Q D A36 36 C Bv- yy R1Q E A36 18 C Bv- yy										
30		B2	2.5	Yes		R1Q E A36 16 C Bv- yy	-19 <mark>-20</mark> -22									
32	DDRII+			•		R1Q F A36 18 C Bv- yy										
33		B4				R1Q F A36 36 C Bv- yy	-19	-20	-22							
						R1Q G A36 18 C Bv- yy										
35 36	QDRII+	B4				R1Q G A36 36 C By- yy				-25						
						R1Q H A36 18 C Bv- yy										
38 39	DDD!!	B2	2.0	No		R1Q H A36 36 C Bv- yy				-25						
41	DDRII+	B4			x18	R1Q J A36 18 C Bv- yy				-25						
42		Б4			x36	R1Q J A36 36 C Bv- yy				-25						
44		B4			x18	R1Q K A36 18 C Bv- yy				-25						
45		D4			x36	R1Q K A36 36 C Bv- yy				-23						
47		B2	2.0	Yes		R1Q L A36 18 C Bv- yy				-25						
48	DDRII+	DZ	2	7		R1Q L A36 36 C Bv- yy				-23						
50		B4				R1Q M A36 18 C Bv- yy				-25						
51					x36	R1Q M A36 36 C Bv- yy										

^{1. &}quot;yy" represents the speed bin. "R1QAA3636CBG-20" can operate at 500 MHz(max) of frequency, for example. 2. "v" represents the package size. If "v" = "G" then size is 15 x 17 mm, and if "v" = "A" then 13 x 15 mm.

Pin Arrangement

R1Q3A3636 (Top) / R1QA(G)A3636 (Mid) / R1QD(K)A3636 (Bottom)

	1	2	3	4	5	6	7	8	9	10	11
Α	/CQ	NC	NC	/W	/BW2	/K	/BW1	/R	SA	NC	CQ
В	Q27	Q18	D18	SA	/BW3	K	/BW0	SA	D17	Q17	Q8
С	D27	Q28	D19	V _{ss}	SA	NC	SA	V _{ss}	D16	Q7	D8
D	D28	D20	Q19	V_{SS}	V _{ss}	V _{SS}	V _{ss}	V_{SS}	Q16	D15	D7
Е	Q29	D29	Q20	V_{DDQ}	V _{ss}	V _{SS}	V _{ss}	V_{DDQ}	Q15	D6	Q6
F	Q30	Q21	D21	V_{DDQ}	V_{DD}	V_{ss}	V_{DD}	V_{DDQ}	D14	Q14	Q5
G	D30	D22	Q22	V_{DDQ}	V_{DD}	V _{SS}	V_{DD}	V_{DDQ}	Q13	D13	D5
Н	/DOFF	V_{REF}	V_{DDQ}	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	V_{DDQ}	V_{REF}	ZQ
J	D31	Q31	D23	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	D12	Q4	D4
K	Q32	D32	Q23	V_{DDQ}	V_{DD}	V _{SS}	V_{DD}	V_{DDQ}	Q12	D3	Q3
L	Q33	Q24	D24	V_{DDQ}	V _{ss}	V _{SS}	V _{ss}	V_{DDQ}	D11	Q11	Q2
М	D33	Q34	D25	V _{ss}	V _{ss}	V _{ss}	V _{ss}	V _{ss}	D10	Q1	D2
N	D34	D26	Q25	V_{SS}	SA	SA	SA	V _{ss}	Q10	D9	D1
Р	Q35	D35	Q26	SA	SA	C QVLD QVLD	SA	SA	Q9	D0	Q0
R	TDO	TCK	SA	SA	SA	/C NC ODT	SA	SA	SA	TMS	TDI

(Top View)

Top ←R1Q3A3636 Mid ←R1QA(G)A3636 Bottom ←R1QD(K)A3636

Notes: 1. Address expansion order for future higher density SRAMs: $10A \rightarrow 2A \rightarrow 7A \rightarrow 5B$.

2. NC pins can be left floating or connected to $0V \sim V_{DDQ}$.

R1Q3A3618 (Top) / R1QA(G)A3618 (Mid) / R1QD(K)A3618 (Bottom)

	1	2	3	4	5	6	7	8	9	10	11
Α	/CQ	NC	SA	/W	/BW1	/K	NC	/R	SA	NC	CQ
В	NC	Q9	D9	SA	NC	K	/BW0	SA	NC	NC	Q8
С	NC	NC	D10	V _{ss}	SA	NC	SA	V _{ss}	NC	Q7	D8
D	NC	D11	Q10	V_{SS}	V _{ss}	V _{ss}	V _{ss}	V_{SS}	NC	NC	D7
Е	NC	NC	Q11	V_{DDQ}	V_{SS}	V_{SS}	V _{ss}	V_{DDQ}	NC	D6	Q6
F	NC	Q12	D12	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	NC	Q5
G	NC	D13	Q13	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	NC	D5
Н	/DOFF	V_{REF}	V_{DDQ}	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	V_{DDQ}	V_{REF}	ZQ
J	NC	NC	D14	V_{DDQ}	V_{DD}	V _{ss}	V_{DD}	V_{DDQ}	NC	Q4	D4
K	NC	NC	Q14	V_{DDQ}	V_{DD}	V_{SS}	V_{DD}	V_{DDQ}	NC	D3	Q3
L	NC	Q15	D15	V_{DDQ}	V_{SS}	V_{SS}	V_{SS}	V_{DDQ}	NC	NC	Q2
М	NC	NC	D16	V_{SS}	V _{SS}	V_{SS}	V _{ss}	V_{SS}	NC	Q1	D2
N	NC	D17	Q16	V_{SS}	SA	SA	SA	V_{SS}	NC	NC	D1
Р	NC	NC	Q17	SA	SA	C QVLD QVLD	SA	SA	NC	D0	Q0
R	TDO	TCK	SA	SA	SA	/C NC ODT	SA	SA	SA	TMS	TDI
						\ /: ~ \					

(Top View)

Notes: 1. Address expansion order for future higher density SRAMs: $10A \rightarrow 2A \rightarrow 7A \rightarrow 5B$.

2. NC pins can be left floating or connected to $0V \sim V_{DDQ}$.

Pin Arrangement

R1Q3A3609 (Top) / R1QA(G)A3609 (Mid) / R1QD(K)A3609 (Bottom)

	1	2	3	4	5	6	7	8	9	10	11
Α	/CQ	NC	SA	/W	NC	/K	NC	/R	SA	SA	CQ
В	NC	NC	NC	SA	NC	K	/BW	SA	NC	NC	Q4
С	NC	NC	NC	V _{ss}	SA	NC	SA	V _{ss}	NC	NC	D4
D	NC	D5	NC	V _{ss}	V_{SS}	V _{ss}	V_{SS}	V _{ss}	NC	NC	NC
Е	NC	NC	Q5	V_{DDQ}	V_{SS}	V _{ss}	V_{SS}	V_{DDQ}	NC	D3	Q3
F	NC	NC	NC	V_{DDQ}	V_{DD}	V _{SS}	V_{DD}	V_{DDQ}	NC	NC	NC
G	NC	D6	Q6	V_{DDQ}	V_{DD}	V _{SS}	V_{DD}	V_{DDQ}	NC	NC	NC
Н	/DOFF	V_{REF}	V_{DDQ}	V_{DDQ}	V_{DD}	V _{SS}	V_{DD}	V_{DDQ}	V_{DDQ}	V_{REF}	ZQ
J	NC	NC	NC	V_{DDQ}	V_{DD}	V _{SS}	V_{DD}	V_{DDQ}	NC	Q2	D2
K	NC	NC	NC	V_{DDQ}	V_{DD}	V _{ss}	V_{DD}	V_{DDQ}	NC	NC	NC
L	NC	Q7	D7	V_{DDQ}	V_{SS}	V _{SS}	V_{SS}	V_{DDQ}	NC	NC	Q1
М	NC	NC	NC	V_{SS}	V_{SS}	V _{SS}	V_{SS}	V _{SS}	NC	NC	D1
N	NC	D8	NC	V _{ss}	SA	SA	SA	V _{ss}	NC	NC	NC
Р	NC	NC	Q8	SA	SA	C D QVLD QVLD	SA	SA	NC	D0	Q0
R	TDO	тск	SA	SA	SA	C NC ODT	SA	SA	SA	TMS	TDI

(Top View)

Notes: 1. Address expansion order for future higher density SRAMs: $10A \rightarrow 2A \rightarrow 7A \rightarrow 5B$.

2. NC pins can be left floating or connected to 0V \sim V_{DDQ}.

Pin Descriptions

Name	I/O type	Descriptions	Notes
SA	Input	Synchronous address inputs: These inputs are registered and must meet the setup and hold times around the rising edge of K. All transactions operate on a burst-of-four words (two clock periods of bus activity). These inputs are ignored when device is deselected.	
/R	Input	Synchronous read: When low, this input causes the address inputs to be registered and a READ cycle to be initiated. This input must meet setup and hold times around the rising edge of K, and is ignored on the subsequent rising edge of K.	
/W	Input	Synchronous write: When low, this input causes the address inputs to be registered and a WRITE cycle to be initiated. This input must meet setup and hold times around the rising edge of K, and is ignored on the subsequent rising edge of K.	
/BW _x	Input	Synchronous byte writes: When low, these inputs cause their respective byte to be registered and written during WRITE cycles. These signals are sampled on the same edge as the corresponding data and must meet setup and hold times around the rising edges of K and /K for each of the two rising edges comprising the WRITE cycle. See Byte Write Truth Table for signal to data relationship.	
K, /K	Input	Input clock: This input clock pair registers address and control inputs on the rising edge of K, and registers data on the rising edge of K and the rising edge of /K. /K is ideally 180 degrees out of phase with K. All synchronous inputs must meet setup and hold times around the clock rising edges. These balls cannot remain V_{REF} level.	
C, /C (II only)	Input	Output clock: This clock pair provides a user-controlled means of tuning device output data. The rising edge of /C is used as the output timing reference for the first and third output data. The rising edge of C is used as the output timing reference for second and fourth output data. Ideally, /C is 180 degrees out of phase with C. C and /C may be tied high to force the use of K and /K as the output reference clocks instead of having to provide C and /C clocks. If tied high, C and /C must remain high and not to be toggled during device operation. These balls cannot remain V_{REF} level.	1
/DOFF	Input	DLL disable: When low, this input causes the DLL to be bypassed for stable, low frequency operation.	
TMS TDI	Input	IEEE1149.1 test inputs: 1.8 V I/O levels. These balls may be left not connected if the JTAG function is not used in the circuit.	
TCK	Input	IEEE1149.1 clock input: 1.8 V I/O levels. This ball must be tied to $V_{\rm SS}$ if the JTAG function is not used in the circuit.	

Notes:

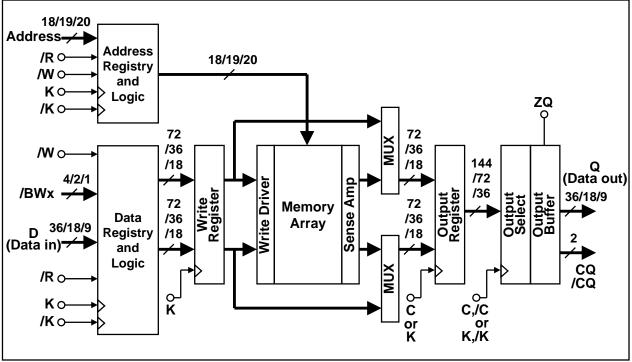
 R1Q2, R1Q3, R1Q4, R1Q5, R1Q6 series have C and /C pins. R1QA, R1QB, R1QC, R1QD, R1QE, R1QF, R1QG, R1QH, R1QJ, R1QK, R1QL, R1QM, R1QN, R1QP series do not have C, /C pins. In the series, K and /K are used as the output reference clocks instead of C and /C. Therefore, hereafter, C and /C represent K and /K in this document.

R1QGA36**CB* / R1QKA36**CB* Series

Name	I/O type	Descriptions	Notes
ZQ	Input	Output impedance matching input: This input is used to tune the device outputs to the system data bus impedance. Q and CQ output impedance are set to $0.2 \times RQ$, where RQ is a resistor from this ball to ground. This ball can be connected directly to V_{DDQ} , which enables the minimum impedance mode. This ball cannot be connected directly to V_{SS} or left unconnected. In ODT (On Die Termination) enable devices, the ODT termination values tracks the value of RQ. The ODT range is selected by ODT control input.	
ODT (II+ only)	Input	ODT control: When low; [Option 1] Low range mode is selected. The impedance range is between 52 Ω and 105 Ω (Thevenin equivalent), which follows 0.3 × RQ for 175 Ω < RQ < 350 Ω . [Option 2] ODT is disabled. When high; High range mode is selected. The impedance range is between 105 Ω and 150 Ω (Thevenin equivalent), which follows 0.6 × RQ for 175 Ω < RQ < 250 Ω . When floating; [Option 1] High range mode is selected. [Option 2] ODT is disabled.	1
D ₀ to D _n	Input	Synchronous data inputs: Input data must meet setup and hold times around the rising edges of K and /K during WRITE operations. See Pin Arrangement figures for ball site location of individual signals. The ×9 device uses D0~D8. D9~D35 should be treated as NC pin. The ×18 device uses D0~D17. D18~D35 should be treated as NC pin. The ×36 device uses D0~D35.	
CQ, /CQ	Output	Synchronous echo clock outputs: The edges of these outputs are tightly matched to the synchronous data outputs and can be used as a data valid indication. These signals run freely and do not stop when Q tristates.	
TDO	Output	IEEE 1149.1 test output: 1.8 V I/O level.	
Q ₀ to Q _n	Output	Synchronous data outputs: Output data is synchronized to the respective C and /C, or to the respective K and /K if C and /C are tied high. This bus operates in response to /R commands. See Pin Arrangement figures for ball site location of individual signals. The ×9 device uses Q0~Q8. Q9~Q35 should be treated as NC pin. The ×18 device uses Q0~Q17. Q18~Q35 should be treated as NC pin. The ×36 device uses Q0~Q35.	
QVLD (II+ only)	Output	Valid output indicator: The Q Valid indicates valid output data. QVLD is edge aligned with CQ and /CQ.	
V _{DD}	Supply	Power supply: 1.8 V nominal. See DC Characteristics and Operating Conditions for range.	2
V _{DDQ}	Supply	Power supply: Isolated output buffer supply. Nominally 1.5 V. See DC Characteristics and Operating Conditions for range.	2
V _{SS}	Supply	Power supply: Ground.	2
V _{REF}	_	HSTL input reference voltage: Nominally $V_{\rm DDQ}/2$, but may be adjusted to improve system noise margin. Provides a reference voltage for the HSTL input buffers.	
NC	_	No connect: These pins can be left floating or connected to $0V \sim V_{DDQ}$.	
Notes:			

- Renesas status: Option 1 = Available, Option 2 = Possible.
 All power supply and ground balls must be connected for proper operation of the device.

Block Diagram (R1QxA3636 / R1QxA3618 / R1QxA3609, x=3,A,D,G,K)



Notes

1. C and /C pins do not exist in II+ series parts.

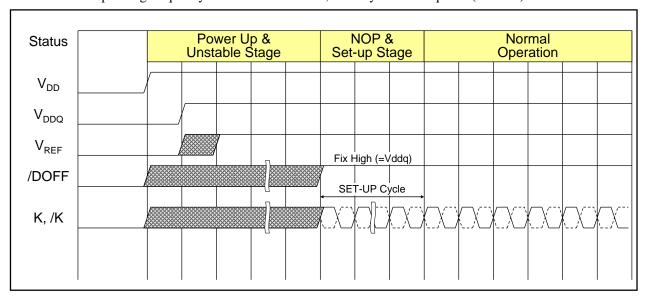
General Description

Power-up and Initialization Sequence

- V_{DD} must be stable before K, /K clocks are applied.
- Recommended voltage application sequence : $V_{SS} \rightarrow V_{DD} \rightarrow V_{DDQ} \& V_{REF} \rightarrow V_{IN}$. (0 V to V_{DD} , $V_{DDQ} < 200$ ms)
- Apply \boldsymbol{V}_{REF} after \boldsymbol{V}_{DDO} or at the same time as $\boldsymbol{V}_{DDO}.$
- Then execute either one of the following three sequences.
- 1. Single Clock Mode (C and /C tied high)
 - Drive /DOFF high (/DOFF can be tied high from the start).
 - Then provide stable clocks (K, /K) for at least 1024 cycles (II series) or 20 us (II+ series).

These meet the QDR common specification of 20 us.

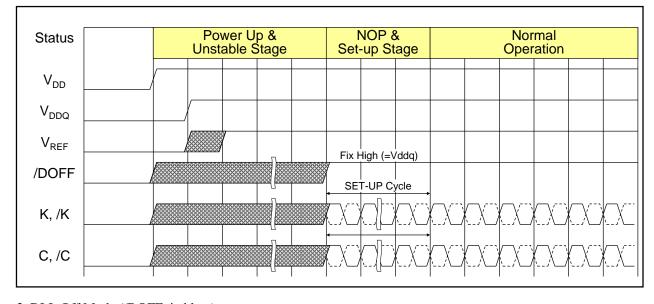
When the operating frequency is less than 180 MHz, 2048 cycles are required (II series).



- 2. Double Clock Mode (C and /C control outputs) (II series only)
 - Drive /DOFF high (/DOFF can be tied high from the start)
 - Then provide stable clocks (K, /K, C, /C) for at least 1024 cycles (II series).

This meets the QDR common specification of 20 us.

When the operating frequency is less than 180 MHz, 2048 cycles are required (II series).



- 3. DLL Off Mode (/DOFF tied low)
 - In the "NOP and setup stage", provide stable clocks (K, /K) for at least 1024 cycles (II series) or 20 us (II+ series). These meet the QDR common specification of 20 us.

R1QGA36**CB* / R1QKA36**CB* Series

DLL Constraints

- 1. DLL uses K clock as its synchronizing input. The input should have low phase jitter which is specified as tKC var.
- 2. The lower end of the frequency at which the DLL can operate is 120 MHz. (Please refer to AC Characteristics table for detail.)
- 3. When the operating frequency is changed or /DOFF level is changed, setup cycles are required again.

Programmable Output Impedance

1. Output buffer impedance can be programmed by terminating the ZQ ball to V_{SS} through a precision resistor (RQ). The value of RQ is five times the output impedance desired. The allowable range of RQ to guarantee impedance matching with a tolerance of 15% is 250 Ω typical. The total external capacitance of ZQ ball must be less than 7.5 pF.

QVLD (Valid data indicator)

(R1QA, R1QB, R1QC, R1QD, R1QE, R1QF, R1QG, R1QH, R1QJ, R1QK, R1QL, R1QM R1QN, R1QP series)

1. QVLD is provided on the QDR-II+ and DDR-II+ to simplify data capture on high speed systems. The Q Valid indicates valid output data. QVLD is activated half cycle before the read data for the receiver to be ready for capturing the data. QVLD is inactivated half cycle before the read finish for the receiver to stop capturing the data. QVLD is edge aligned with CQ and /CQ.

ODT (On Die Termination)

(R1QD, R1QE, R1QF, R1QK, R1QL, R1QM, R1QP series)

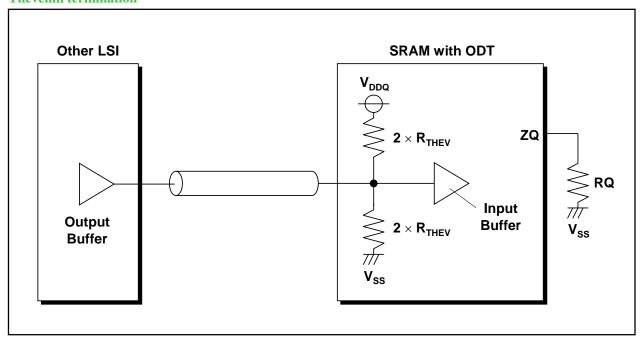
- 1. To reduce reflection which produces noise and lowers signal quality, the signals should be terminated, especially at high frequency. Renesas offers ODT on the input signals to QDR-II+ and DDR-II+ family of devices. (See the ODT pin table)
- 2. In ODT enable devices, the ODT termination values tracks the value of RQ. The ODT range is selected by ODT control input. (See the ODT range table)
- 3. In DDR-II+ devices having common I/O bus, ODT is automatically enabled when the device inputs data and disabled when the device outputs data.
- 4. There is no difference in AC timing characteristics between the SRAMs with ODT and SRAMs without ODT.
- 5. There is no increase in the I_{DD} of SRAMs with ODT, however, there is an increase in the I_{DDQ} (current consumption from the I/O voltage supply) with ODT.

ODT range

ODT control nin	Thevenin equivalen	t resistance (R _{THEV})	Unit	Notes
ODT control pin	Option 1	Option 2	-	6
Low	$0.3 \times RQ$	(ODT disable)	Ω	1, 4
High	$0.6 \times RQ$	0.6 × RQ	Ω	2, 5
Floating	$0.6 \times RQ$	(ODT disable)	Ω	3

- 1. Allowable range of RQ for Option 1 to guarantee impedance matching a tolerance of \pm 20 % is 175 Ω < RQ < 350 Ω .
- 2. Allowable range of RQ to guarantee impedance matching a tolerance of \pm 20 % is 175 Ω < RQ < 250 Ω .
- 3. Allowable range of RQ for Option 1 to guarantee impedance matching a tolerance of \pm 20 % is 175 Ω < RQ < 250 Ω .
- 4. At option 1, ODT control pin is connected to V_{DDQ} through 3.5 k Ω . Therefore it is recommended to connect it to V_{SS} through less than 100 Ω to make it low.
- 5. At option 2, ODT control pin is connected to V_{SS} through 3.5 k Ω . Therefore it is recommended to connect it to V_{DDQ} through less than 100 Ω to make it high.
- 6. Renesas status: Option 1 = Available, Option 2 = Possible. If you need devices with option 2, please contact Renesas sales office.

Thevenin termination



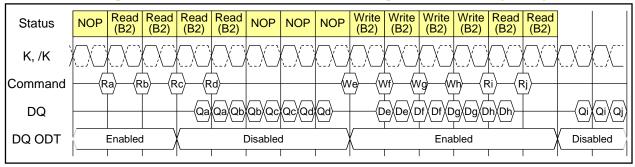
ODT pin (R1QD, R1QE, R1QF, R1QK, R1QL, R1QM, R1QP series)

Pin name	Pin witl	h ODT	ODT On/Off timing	Notes
Finitianie	Option 1	Option 2	-	3
D ₀ ~ D _n in separate I/O devices			Always On	1
DQ ₀ ~ DQ _n in common I/O devices	Yes	Yes	Off: First Read Command + Read Latency - 0.5 cycle On: Last Read Command + Read Latency + BL/2 cycle + 0.5 cycle (See below timing chart)	2
/BW _x	Yes	Yes	Always On	
K, /K	Yes	No	Always On (@ Option 1) Always Off (@ Option 2)	

Notes: 1. Separate I/O devices are R1QD, R1QK, R1QP series.

- 2. Common I/O devices are R1QE, R1QF, R1QL, R1QM series.
- 3. Renesas status: Option 1 = Available, Option 2 = Possible. If you need devices with option 2, please contact Renesas sales office.

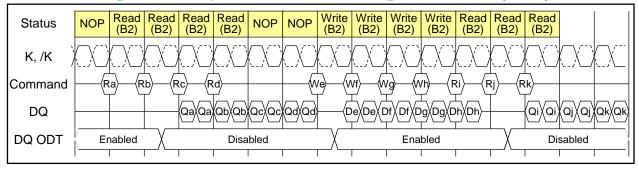
ODT on/off Timing Chart for R1QE series (DDR II+, Burst Length=2, Read Latency=2.5 cycle)



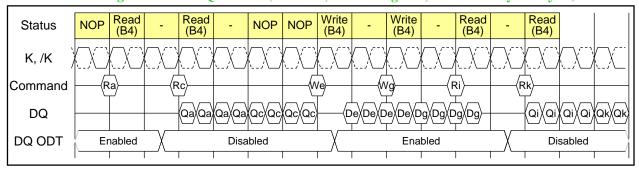
ODT on/off Timing Chart for R1QF series (DDR II+, Burst Length=4, Read Latency=2.5 cycle)

Status	NOP	Read (B4)	-	Read (B4)	-	NOP	NOP	NOP	Write (B4)	-	Write (B4)	-	Read (B4)	-	
K, /K															
Command		[a]		.c)——				<u> </u>	/e}——	<u> </u>	/9	F	Ri}		
DQ				——(Qa)	Qa/Qa	Qa/Qc	Qc/Qc	Qc}—	——©	pe/De/D	eVDeVD		g Dg		—Qi\Qi\Qi\Qi
DQ ODT		Enabled			[Disable	d I				Ena	bled			Disabled

ODT on/off Timing Chart for R1QL series (DDR II+, Burst Length=2, Read Latency=2.0 cycle)



ODT on/off Timing Chart for R1QM series (DDR II+, Burst Length=4, Read Latency=2.0 cycle)



Notes

1. ODT on/off switching timings are edge aligned with CQ or /CQ.

K Truth Table

K	/R	/W	D or Q								
			Data in								
↑	H*7	L*8	1	Input data		D(A+1)	D(A+2)	D(A+3)			
			Input		K(t+1)↑	/K(t+1)↑	K(t+2)↑	/K(t+2)↑			
			Data o	ut							
	1 *0			•	Q(A+0)	Q(A+1)	Q(A+2)	Q(A+3)			
Ť	L°	×	Input	RL*9=1.5	/C(t+1)↑	C(t+2)↑	/C(t+2) ↑	C(t+3)↑			
			clock	RL=2.0	C(t+2)↑	/C(t+2)↑	C(t+3)↑	/C(t+3)↑			
			for Q	RL=2.5	/C(t+2)↑	C(t+3)↑	/C(t+3)↑	C(t+4)↑			
1	Η	Н	D = ×	or $Q = H$	igh-Z						
Stopped	×	×	Previous state								
	† †	↑ H*7 ↑ L*8	↑ H*7 L*8 ↑ L*8 ×	↑ H*7 L*8 Data in I Data in I Data in I Data in I Data o I Data o I Data o I Data o O I Input clock for Q ↑ H H D = ×	↑ H*7 L*8 Data in Input data Input clock Data out Output data Input RL*9=1.5 Clock For Q RL=2.5 ↑ H H D = × or Q = H	$\uparrow H^{*7} L^{*8} \begin{array}{ c c c c c }\hline Data \ in \\\hline & Input \\ clock \\\hline & Input \\ clock \\\hline & K(t+1) \uparrow \\\hline \\\hline Data \ out \\\hline & Output \\ data \\\hline & Input \\ data \\\hline & RL^{*9}=1.5 \ /C(t+1) \uparrow \\ clock \\ for \ Q \\\hline & RL=2.0 \ C(t+2) \uparrow \\ for \ Q \\\hline \\ & RL=2.5 \ /C(t+2) \uparrow \\\hline \\ \uparrow H H D=\times or Q=High-Z \\\hline \end{array}$	$\uparrow H^{*7} L^{*8} \frac{\text{Data in}}{\text{Input}} D(A+0) D(A+1)$ $= \frac{\text{Input}}{\text{clock}} K(t+1) \uparrow /K(t+1) \uparrow$ $\uparrow L^{*8} \times \frac{\text{Data out}}{\text{Output}} Q(A+0) Q(A+1)$ $= \frac{\text{Input}}{\text{clock}} \frac{\text{RL}^{*9}=1.5}{\text{for Q}} \frac{\text{RL}=2.0}{\text{RL}=2.5} /C(t+2) \uparrow C(t+2) \uparrow$ $= \frac{\uparrow}{\text{RL}=2.5} /C(t+2) \uparrow C(t+3) \uparrow$	$\uparrow H^{*7} L^{*8} \frac{\text{Data in}}{\text{Input}} D(A+0) D(A+1) D(A+2) \\ \frac{\text{Input}}{\text{clock}} K(t+1) \uparrow /K(t+1) \uparrow K(t+2) \uparrow \\ \frac{\text{Data out}}{\text{Data out}} Q(A+0) Q(A+1) Q(A+2) \\ \frac{\text{Input}}{\text{clock}} RL^{*9} = 1.5 /C(t+1) \uparrow C(t+2) \uparrow /C(t+2) \uparrow \\ \text{For Q} RL = 2.0 C(t+2) \uparrow /C(t+2) \uparrow /C(t+3) \uparrow \\ \uparrow H H D = \times \text{or} Q = \text{High-Z}$			

- 1. H: high level, L: low level, ×: don't care, ↑: rising edge.
- 2. Data inputs are registered at K and /K rising edges. Data outputs are delivered at C and /C rising edges, except if C and /C are high, then data outputs are delivered at K and /K rising edges.
- 3. /R and /W must meet setup/hold times around the rising edges (low to high) of K and are registered at the rising edge of K.
- 4. This device contains circuitry that will ensure the outputs will be in high-Z during power-up.
- 5. Refer to state diagram and timing diagrams for clarification.
- 6. When clocks are stopped, the following cases are recommended; the case of K = low, /K = high, C = low and /C = high, or the case of K = high, /K = low, C = high and /C = low. This condition is not essential, but permits most rapid restart by overcoming transmission line charging symmetrically.
- 7. If this signal was low to initiate the previous cycle, this signal becomes a "don't care" for this operation; however, it is strongly recommended that this signal be brought high, as shown in the truth table.
- 8. This signal was high on previous K clock rising edge. Initiating consecutive READ or WRITE operations on consecutive K clock rising edges is not permitted. The device will ignore the second request.
- 9. RL = Read Latency (unit = cycle).

Byte Write Truth Table (x 36)

Operation	K	/K	/BW0	/BW1	/BW2	/BW3
Write D0 to D35	↑	-	L	L	L	L
White Do to Doo	-	↑	L	L	L	L
Write D0 to D8	↑	-	L	Н	Н	Н
Wille Do to Do	-	↑	L	Н	Н	Н
Write D9 to D17	↑	ı	Н	L	Н	Н
White D9 to D17		↑	Н	L	Н	Н
Write D18 to D26	↑	-	Н	Н	L	Н
Write D16 to D26	-	↑	Н	Н	L	Н
Write D27 to D35	↑	•	Н	Н	Н	L
Wille D27 to D35	-	↑	Н	Н	Н	L
Write nothing	↑	-	Н	Н	Н	Н
Write nothing	-	1	Н	Н	Н	Н

Notes:

- 1. H: high level, L: low level, ↑: rising edge.
- 2. Assumes a WRITE cycle was initiated. /BWx can be altered for any portion of the BURST WRITE operation provided that the setup and hold requirements are satisfied.

Byte Write Truth Table (x 18)

Operation	K	/K	/BW0	/BW1
Write D0 to D17	↑	-	L	L
White Do to D17		↑	L	L
Write D0 to D8	↑	-	L	Н
Wille DO to Do	-	1	L	Н
Write D9 to D17	↑	-	Н	L
White D9 to D17	-	1	Н	L
Write nothing	1	-	Н	Н
Write nothing	-	1	Н	Н

Notes:

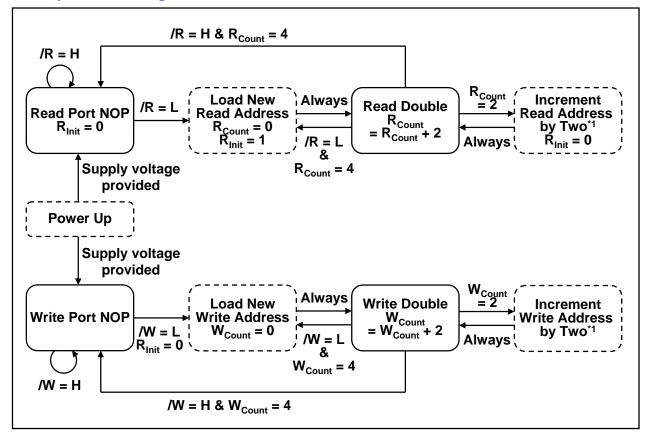
- 1. H: high level, L: low level, ↑: rising edge.
- 2. Assumes a WRITE cycle was initiated. /BWx can be altered for any portion of the BURST WRITE operation provided that the setup and hold requirements are satisfied.

Byte Write Truth Table (x 9)

Operation	K	/K	/BW
Write D0 to D8	↑	-	L
VVIIILE DU 10 Do	-	1	L
Write nothing	↑	-	Н
Write nothing	-	1	Н

- 1. H: high level, L: low level, ↑: rising edge.
- 2. Assumes a WRITE cycle was initiated. /BWx can be altered for any portion of the BURST WRITE operation provided that the setup and hold requirements are satisfied.

Bus Cycle State Diagram



- 1. The address is concatenated with two additional internal LSBs to facilitate burst operation. The address order is always fixed as: xxx...xxx+0, xxx...xxx+1, xxx...xxx+2, xxx...xxx+3. Bus cycle is terminated at the end of this sequence (burst count = 4).
- 2. Read and write state machines can be active simultaneously. Read and write cannot be simultaneously initiated. Read takes precedence.
- 3. State machine control timing sequence is controlled by K.

Absolute Maximum Ratings

Parameter	Symbol	Rating	Unit	Notes
Input voltage on any ball	V _{IN}	-0.5 to V _{DD} + 0.5 (2.5 V max.)	٧	1, 4
Input/output voltage	V _{I/O}	–0.5 to V _{DDQ} + 0.5 (2.5 V max.)	V	1, 4
Core supply voltage	V_{DD}	−0.5 to 2.5	V	1, 4
Output supply voltage	V_{DDQ}	-0.5 to V_{DD}	V	1, 4
Junction temperature	Tj	+125 (max)	°C	5
Storage temperature	T _{STG}	-55 to +125	°C	

Notes:

- 1. All voltage is referenced to V_{SS} .
- 2. Permanent device damage may occur if Absolute Maximum Ratings are exceeded. Functional operation should be restricted the Operation Conditions. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.
- 3. These CMOS memory circuits have been designed to meet the DC and AC specifications shown in the tables after thermal equilibrium has been established.
- 4. The following supply voltage application sequence is recommended: V_{SS} , V_{DD} , V_{DDQ} , V_{REF} then V_{IN} . Remember, according to the Absolute Maximum Ratings table, V_{DDQ} is not to exceed 2.5 V, whatever the instantaneous value of V_{DDQ} .
- Some method of cooling or airflow should be considered in the system. (Especially for high frequency or ODT parts)

Recommended DC Operating Conditions

Parameter	Symbol	Min	Тур	Max	Unit	Notes
Power supply voltage core	V_{DD}	1.7	1.8	1.9	V	1
Power supply voltage I/O	V_{DDQ}	1.4	1.5	V_{DD}	V	1, 2
Input reference voltage I/O	V_{REF}	0.68	0.75	0.95	V	3
Input high voltage	V _{IH (DC)}	V _{REF} + 0.1		$V_{DDQ} + 0.3$	V	1, 4, 5
Input low voltage	V _{IL (DC)}	-0.3		V _{REF} – 0.1	V	1, 4, 5

- 1. At power-up, V_{DD} and V_{DDQ} are assumed to be a linear ramp from 0V to V_{DD} (min.) or V_{DDQ} (min.) within 200ms. During this time $V_{DDQ} < V_{DD}$ and $V_{IH} < V_{DDQ}$. During normal operation, V_{DDQ} must not exceed V_{DD} .
- 2. Please pay attention to Tj not to exceed the temperature shown in the absolute maximum ratings table due to current from V_{DDQ} .
- 3. Peak to peak AC component superimposed on V_{REF} may not exceed 5% of V_{REF} .
- 4. These are DC test criteria. The AC V_{IH} / V_{IL} levels are defined separately to measure timing parameters.
- $\begin{array}{ll} \text{5. Overshoot: } V_{\text{IH (AC)}} \leq V_{\text{DDQ}} + 0.5 \text{ V for } t \leq t_{\text{KHKH}}/2 \\ \text{Undershoot: } V_{\text{IL (AC)}} \geq -0.5 \text{ V for } t \leq t_{\text{KHKH}}/2 \\ \text{During normal operation, } V_{\text{IH(DC)}} \text{ must not exceed } V_{\text{DDQ}} \text{ and } V_{\text{IL(DC)}} \text{ must not be lower than } V_{\text{SS}}. \\ \end{array}$

R1QGA36**CB* / R1QKA36**CB* Series

DC Characteristics

$$(Ta = 0 \sim +70 ^{\circ}\text{C @ R1Q*A*****BG-**} \textbf{R*****BG-**} \textbf{R******BG-**} \textbf{I*** series}, \quad Ta = -40 \sim +85 ^{\circ}\text{C @ R1Q*A*****} \textbf{BG-**} \textbf{I*** series}) \\ (V_{DD} = 1.8V \pm 0.1V, V_{DDO} = 1.5V, V_{REF} = 0.75V)$$

Operating Supply Current (Write / Read)

Symbol = I_{DD} . Unit = mA. See Notes 1, 2 and 3 in the page after next.

								QI	OR II+	/ DDR	II+		C	DR II	/ DDR	II
	uct e	st th	cy le)	T	ni- n	Frequency (max) (MHz)	533	500	450	400	375	333	333	300	250	200
No	Product Type	Burst Length	Latency (Cycle)	ODT	Organi- zation	Cycle Time (min) (ns)	1.875	2.00	2.22	2.50	2.66	3.00	3.00	3.30	4.00	5.00
						Part Number ↓ yy →	-19	-20	-22	-25	-27	-30	-30	-33	-40	-50
17	QDRII+	B4				R1Q A A36 18 C Bv- yy	1220	1160	1070							
18		דע				R1Q A A36 36 C Bv- yy	1280	1220	1130							
20		B2	2.5	S N		R1Q B A36 18 C Bv- yy	1030	990	920							
21	DDRII+		2	2		R1Q B A36 36 C Bv- yy	1110	1060	990							
23 24		B4				R1Q C A36 18 C Bv- yy	820	790	750							
						R1Q C A36 36 C Bv- yy	880	850	800							
26	QDRII+	B4				R1Q D A36 18 C Bv- yy	1220	1160	1070							
27						R1Q D A36 36 C Bv- yy	1280	1220	1130							
29		B2	2.5	Yes		R1Q E A36 18 C Bv- yy	1030	990	920							
30	DDRII+		7	Υ		R1Q E A36 36 C Bv- yy	1110	1060	990							
32		В4				R1Q F A36 18 C Bv- yy	820	790	750							
33						R1Q F A36 36 C Bv- yy	880	850	800							
35	QDRII+	В4				R1Q G A36 18 C Bv- yy				980						
36						R1Q G A36 36 C Bv- yy				1060						
38		B2	2.0	9 N		R1Q H A36 18 C Bv- yy				850						
39	DDRII+		7	_		R1Q H A36 36 C Bv- yy				910						
41		B4				R1Q J A36 18 C Bv- yy				710						
42						R1Q J A36 36 C Bv- yy				760						
44	QDRII+	В4				R1Q K A36 18 C Bv- yy				980						
45						R1Q K A36 36 C Bv- yy				1060						
47		B2	2.0	Yes		R1Q L A36 18 C Bv- yy				850						
48	DDRII+		. 4	_		R1Q L A36 36 C Bv- yy				910						
50		B4				R1Q M A36 18 C Bv- yy				710						
51					x36	R1Q M A36 36 C Bv- yy				760						

^{1. &}quot;yy" represents the speed bin. "R1QAA3636CBG-20" can operate at 500 MHz(max) of frequency, for example. 2. "v" represents the package size. If "v" = "G" then size is 15 x 17 mm, and if "v" = "A" then 13 x 15 mm.

Standby Supply Current (NOP)

Symbol = I_{SB1} . Unit = mA. See Notes 2, 4 and 5 in the next page.

								QI	OR II+	/ DDR	II+		C	DR II	/ DDR	II
	uct e	t) t	cy e)	_	ni- n	Frequency (max) (MHz)	533	500	450	400	375	333	333	300	250	200
No	Product Type	Burst Length	Latency (Cycle)	ODT	Organi- zation	Cycle Time (min) (ns)	1.875	2.00	2.22	2.50	2.66	3.00	3.00	3.30	4.00	5.00
						Part Number ↓ yy →	-19	-20	-22	-25	-27	-30	-30	-33	-40	-50
17	QDRII+	B4			x18	R1Q A A36 18 C Bv- yy	870	830	780							
18	QDINIT	D4				R1Q A A36 36 C Bv- yy	910	870	810							
20		B2	2.5	N _O		R1Q B A36 18 C Bv- yy	870	840	780							
21	DDRII+	-	2	2		R1Q B A36 36 C Bv- yy	960	920	860							
23 24	DDIKIII	B4				R1Q C A36 18 C Bv- yy	690	660	630							
						R1Q C A36 36 C Bv- yy	730	710	670							
26	QDRII+	B4				R1Q D A36 18 C Bv- yy	870	830	780							
27	QD11111					R1Q D A36 36 C Bv- yy	910	870	810							
29 30 32		B2	2.5	Yes		R1Q E A36 18 C Bv- yy	870	840	780							
30	DDRII+		7	Υ		R1Q E A36 36 C Bv- yy	960	920	860							
32	55 11111	B4				R1Q F A36 18 C Bv- yy	690	660	630							
33						R1Q F A36 36 C Bv- yy	730	710	670							
35	QDRII+	B4				R1Q G A36 18 C Bv- yy				720						
36						R1Q G A36 36 C Bv- yy				770						
38		B2	2.0	No		R1Q H A36 18 C Bv- yy				720						
39	DDRII+		2	2		R1Q H A36 36 C Bv- yy				790						
41		B4				R1Q J A36 18 C Bv- yy				590						
42						R1Q J A36 36 C Bv- yy				630						
44	QDRII+	B4				R1Q K A36 18 C Bv- yy				720						
45						R1Q K A36 36 C Bv- yy				770						
47		B2	2.0	Yes		R1Q L A36 18 C Bv- yy				720						
48	DDRII+		7	\		R1Q L A36 36 C Bv- yy				790						
50		B4				R1Q M A36 18 C Bv- yy				590						
51					x36	R1Q M A36 36 C Bv- yy				630						

^{1. &}quot;yy" represents the speed bin. "R1QAA3636CBG-20" can operate at 500 MHz(max) of frequency, for example. 2. "v" represents the package size. If "v" = "G" then size is 15 x 17 mm, and if "v" = "A" then 13 x 15 mm.

Leakage Currents & Output Voltage

Parameter	Symbol	Min	Max	Unit	Test condition	Notes
Input leakage current	I _{LI}	-2	2	μΑ		10
Output leakage current	I_{LO}	- 5	5	μΑ		11
Output high voltage	V _{OH} (Low)	V _{DDQ} - 0.2	V_{DDQ}	V	$ I_{OH} \le 0.1 \text{ mA}$	8, 9
	V_{OH}	V _{DDQ} /2 - 0.12	V _{DDQ} /2 + 0.12	V	Note 6	8, 9
Output low voltage	V _{OL} (Low)	V _{ss}	0.2	V	I _{OL} ≤ 0.1 mA	8, 9
	V_{OL}	V _{DDQ} /2 - 0.12	V _{DDQ} /2 + 0.12	V	Note 7	8, 9

- 1. All inputs (except ZQ, V_{REF}) are held at either V_{IH} or V_{IL} .
- 2. $I_{OUT} = 0 \text{ mA}$. $V_{DD} = V_{DD} \text{ max}$, $t_{KHKH} = t_{KHKH} \text{ min}$.
- 3. Operating supply currents (I_{DD}) are measured at 100% bus utilization. I_{DD} of QDR family is current of device with 100% write and 100% read cycle. I_{DD} of DDR family is current of device with 100% write cycle (if I_{DD} (Write) > I_{DD} (Read)) or 100% read cycle (if I_{DD} (Write) < I_{DD} (Read)).
- 4. All address / data inputs are static at either $V_{IN} > V_{IH}$ or $V_{IN} < V_{IL}$.
- 5. Reference value. (Condition = NOP currents are valid when entering NOP after all pending READ and WRITE cycles are completed.)
- 6. Outputs are impedance-controlled. $|I_{OH}| = (V_{DDQ}/2)/(RQ/5)$ for values of 175 $\Omega \le RQ \le 350~\Omega$.
- 7. Outputs are impedance-controlled. $I_{OL} = (V_{DDQ}/2)/(RQ/5)$ for values of 175 $\Omega \le RQ \le 350 \ \Omega$.
- 8. AC load current is higher than the shown DC values. AC I/O curves are available upon request.
- 9. HSTL outputs meet JEDEC HSTL Class I and Class II standards.
- 10. $0 \le V_{IN} \le V_{DDQ}$ for all input balls (except V_{REF} , ZQ, TCK, TMS, TDI ball). If R1QD, R1QE, R1QF, R1QK, R1QL, R1QM, R1QP series, balls with ODT do not follow this spec.
- 11. $0 \le V_{OUT} \le V_{DDQ}$ (except TDO ball), output disabled.

Thermal Resistance

Parameter	Symbol	Airflow	Тур	Unit	Test condition	Notes
Junction to Ambient	θ_{JA}	1 m/s	11.0	°C/W	EIA/JEDEC JESD51	1
Junction to Case	θ_{JC}	-	4.4	C/VV	EIA/JEDEC JESDST	ı

Notes:

1. These parameters are calculated under the condition. These are reference values.

2. Tj = Ta +
$$\theta_{JA}$$
 × Pd

$$Tj = Tc + \theta_{JC} \times Pd$$

where

Tj: junction temperature when the device has achieved a steady-state after application of Pd (°C)

Ta: ambient temperature (°C)

Tc: temperature of external surface of the package or case (°C)

θ_{JA}: thermal resistance from junction-to-ambient (°C/W)

 θ_{JC} : thermal resistance from junction-to-case (package) (°C/W)

Pd: power dissipation that produced change in junction temperature (W) (cf.JESD51-2A)

Capacitance

(Ta = +25°C, Frequency = 1.0MHz, $V_{DD} = 1.8V$, $V_{DDO} = 1.5V$)

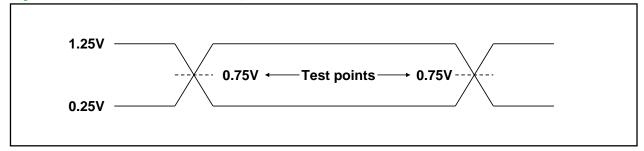
Parameter	Symbol	Min	Тур	Max	Unit	Test condition	Notes
Input capacitance (SA, /R, /W, /BW, D(separate))	C _{IN}	_	4	5	pF	V _{IN} = 0 V	1, 2
Clock input capacitance (K, /K, C, /C)	C _{CLK}	_	4	5	pF	V _{CLK} = 0 V	1, 2
Output capacitance (Q(separate), DQ(common), CQ, /CQ)	C _{I/O}	_	5	6	pF	V _{I/O} = 0 V	1, 2

Notes:

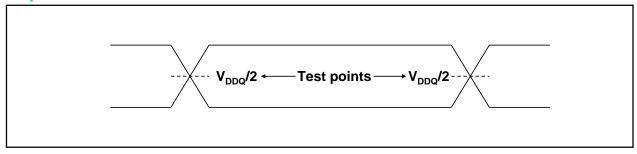
- 1. These parameters are sampled and not 100% tested.
- 2. Except JTAG (TCK, TMS, TDI, TDO) pins.

AC Test Conditions

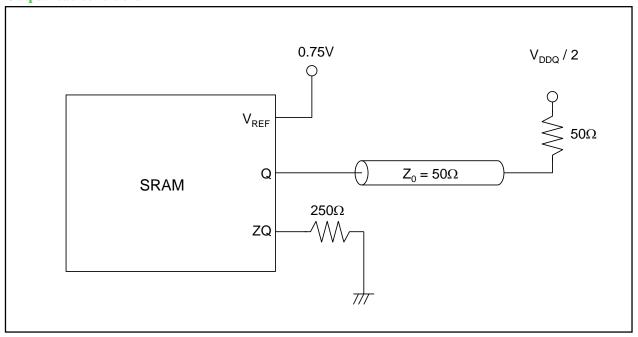
Input waveform (Rise/fall time ≤ 0.3 ns)



Output waveform



Output load conditions



AC Operating Conditions

Parameter	Symbol	Min	Тур	Max	Unit	Notes
Input high voltage	V _{IH (AC)}	V _{REF} + 0.2	_		7	1, 2, 3, 4
Input low voltage	V _{IL (AC)}		_	$V_{REF} - 0.2$	7	1, 2, 3, 4

- 1. All voltages referenced to V_{SS} (GND). During normal operation, V_{DDQ} must not exceed V_{DD} .
- 2. These conditions are for AC functions only, not for AC parameter test.
- 3. Overshoot: $V_{IH (AC)} \le V_{DDQ} + 0.5 \text{ V}$ for $t \le t_{KHKH}/2$ Undershoot: $V_{IL (AC)} \ge -0.5 \text{ V}$ for $t \le t_{KHKH}/2$ Control input signals may not have pulse widths less than t_{KHKL} (min) or operate at cycle rates less than t_{KHKH} (min).
- 4. To maintain a valid level, the transitioning edge of the input must:
 - a. Sustain a constant slew rate from the current AC level through the target AC level, $V_{\rm IL\ (AC)}$ or $V_{\rm IH\ (AC)}$.
 - b. Reach at least the target AC level.
 - c. After the AC target level is reached, continue to maintain at least the target DC level, $V_{\text{IL (DC)}}$ or $V_{\text{IH (DC)}}$.

AC Characteristics (Read Latency = 2.0 cycle)

 $(Ta = 0 \sim +70^{\circ}C @ R1Q*A****BG-**R** series)$

 $(Ta = -40 \sim +85^{\circ}C @ R1Q*A****BG-**I** series)$

 $(V_{DD} = 1.8V \pm 0.1V, \, V_{DDQ} = 1.5V, \, V_{REF} = 0.75V)$

		-1	9	-2	20	-2	22	-2	25	-2	27	-3	30		
Parameter	Symbol	Min	Max	Unit	Notes										
Clock															
Average clock cycle time (K, /K)	t _{KHKH}	1.875	4.00	2.00	4.00	2.22	4.00	2.50	4.00	2.66	4.00	3.00	4.00	ns	
Clock high time (K, /K)	t _{KHKL}	0.40		0.40		0.40		0.40		0.40		0.40		Cy- cle	
Clock low time (K, /K)	t _{KLKH}	0.40		0.40		0.40		0.40		0.40		0.40		Cy- cle	
Clock to /clock (K to /K)	t _{KH/KH}	0.425		0.425		0.425		0.425		0.425		0.425		Cy- cle	
/Clock to clock (/K to K)	t _{/KHKH}	0.425		0.425	_	0.425	_	0.425	_	0.425	_	0.425		Cy- cle	
_	_													_	
DLL Timing															
Clock phase jitter (K, /K)	t _{KC} var		0.15	_	0.15	_	0.15	_	0.20	_	0.20	_	0.20	ns	3
DLL lock time (K)	t _{KC} lock	20		20		20		20		20		20		us	2
K static to DLL reset	t _{KC} reset	30		30		30	_	30		30		30		ns	7
Output Times															
K, /K high to output valid	t _{CHQV}		0.55	—	0.55		0.55	—	0.55	—	0.55	—	0.55	ns	
K, /K high to output hold	t _{CHQX}	-0.35		-0.35		-0.35		-0.35		-0.35		-0.35		ns	
K, /K high to echo clock valid	t _{CHCQV}		0.55		0.55		0.55	_	0.55	_	0.55	_	0.55	ns	
K, /K high to echo clock hold	t _{CHCQX}	-0.35		-0.35		-0.35		-0.35	_	-0.35		-0.35		ns	
CQ, /CQ high to output valid	t _{cqHQV}		0.15		0.15		0.15		0.20		0.20		0.20	ns	4, 7
CQ, /CQ high to output hold	t _{cqHqx}	-0.15		-0.15		-0.15		-0.20		-0.20		-0.20		ns	4, 7
K, /K high to output high-Z	t _{CHQZ}		0.55		0.55		0.55		0.55		0.55		0.55	ns	5, 6
K, /K high to output low-Z	t _{CHQX1}	-0.35		-0.35		-0.35		-0.35		-0.35		-0.35		ns	5
/CQ high to QVLD valid	t _{QVLD}	-0.15	0.15	-0.15	0.15	-0.15	0.15	-0.20	0.20	-0.20	0.20	-0.20	0.20	ns	7

R1QGA36**CB* / R1QKA36**CB* Series

Devemeter	Cumbal	-1	19	-2	20	-2	22	-2	25	-2	27	-3	0	Unit	Notes
Parameter	Symbol	Min	Max	Unit	notes										
Setup Times															
Address valid to	t _{avkh} for QDR	0.30		0.33		0.40		0.40		0.40		0.40		ns	1, 8
K rising edge	t _{avkh} for DDR	0.30		0.33		0.40	_	0.40	_	0.40		0.40		113	1, 0
Control inputs	t _{IVKH} for QDR	0.30		0.33		0.40	_	0.40	_	0.40		0.40		ns	1, 8
K rising edge	t _{IVKH} for DDR	0.30		0.33		0.40		0.40		0.40		0.40		110	1, 0
Data-in valid to K, /K rising edge	t _{DVKH}	0.20		0.22		0.25	_	0.28	_	0.28	_	0.28	_	ns	1, 9
Hold Times															
K rising edge	t _{KHAX} for QDR	0.30	_	0.33		0.40	_	0.40	_	0.40		0.40		20	1 0
to address hold	t _{KHAX} for DDR	0.30	_	0.33		0.40	_	0.40		0.40		0.40		ns	1, 8
K rising edge to control inputs	t _{KHIX} for QDR	0.30		0.33		0.40		0.40		0.40		0.40		ns	1, 8
hold	t _{kHIX} for DDR	0.30		0.33		0.40		0.40		0.40		0.40			., 0
K, /K rising edge to data-in hold	t _{KHDX}	0.20		0.22		0.25		0.28		0.28		0.28	_	ns	1, 9

Notes:

- 1. This is a synchronous device. All addresses, data and control lines must meet the specified setup and hold times for all latching clock edges.
- 2. V_{DD} slew rate must be less than 0.1 V DC per 50 ns for DLL lock retention. DLL lock time begins once V_{DD} and input clock are stable.

It is recommended that the device is kept inactive during these cycles.

This specification meets the QDR common spec. of 20 us.

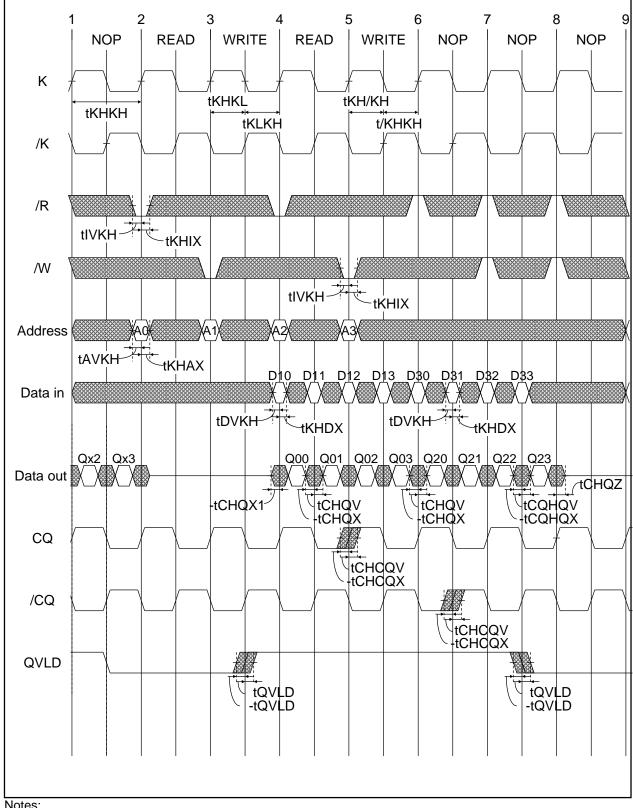
- 3. Clock phase jitter is the variance from clock rising edge to the next expected clock rising edge.
- 4. Echo clock is very tightly controlled to data valid / data hold. By design, there is a ± 0.1 ns variation from echo clock to data. The datasheet parameters reflect tester guardbands and test setup variations.
- 5. Transitions are measured ± 100 mV from steady-state voltage.
- 6. At any given voltage and temperature t_{CHQZ} is less than t_{CHQX1} and t_{CHQV} .
- 7. These parameters are sampled.
- 8. t_{AVKH} , t_{IVKH} , t_{KHAX} , t_{KHIX} spec is determined by the actual frequency regardless of Part Number (Marking Name). The following is the spec for the actual frequency.
 - 0.30 ns for ≤533MHz & >500MHz
 - 0.33 ns for ≤500MHz & >450MHz
 - 0.40 ns for ≤450MHz & ≥250MHz
- 9. t_{DVKH}, t_{KHDX} spec is determined by the actual frequency regardless of Part Number (Marking Name). The following is the spec for the actual frequency.
 - 0.20 ns for ≤533MHz & >500MHz
 - 0.22 ns for ≤500MHz & >450MHz
 - 0.25 ns for ≤450MHz & >400MHz
 - 0.28 ns for ≤400MHz & >300MHz
 - 0.30 ns for ≤300MHz & ≥250MHz

Remarks:

- Test conditions as specified with the output loading as shown in AC Test Conditions unless otherwise noted.
- 2. Control input signals may not be operated with pulse widths less than t_{KHKI} (min).
- 3. V_{DDQ} is +1.5 V DC. V_{REF} is +0.75 V DC.
- 4. Control signals are /R, /W (QDR series), /LD, R-/W (DDR series), /BW, /BW0, /BW1, /BW2 and /BW3. Setup and hold times of /BWx signals must be the same as those of Data-in signals.

Timing Waveforms

Read and Write Timing (QDRII+, B4, Read Latency = 2.0 cycle)



Notes:

- 1. Q00 refers to output from address A0+0. Q01 refers to output from the next internal burst address following A0, i.e., A0+1.
- 2. Outputs are disabled (high-Z) N clock cycle after the last read cycle. Here, N = Read Latency + Burst Length \times 0.5.
- In this example, if address A2 = A1, then data Q20 = D10, Q21 = D11. Write data is forwarded immediately as read results.
- 4. To control read and write operations, /BW signals must operate at the same timing as Data-in signals.

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JTAG Specification

These products support a limited set of JTAG functions as in IEEE standard 1149.1.

Disabling the Test Access Port

It is possible to use this device without utilizing the TAP. To disable the TAP controller without interfering with normal operation of the device, TCK must be tied to V_{SS} to preclude mid level inputs.

TDI and TMS are internally pulled up and may be unconnected, or may be connected to VDD through a pull up resistor.

TDO should be left unconnected.

Test Access Port (TAP) Pins

Symbol I/O	Pin assignments	Description	Notes
TCK	2R	Test clock input. All inputs are captured on the rising edge of TCK and all outputs propagate from the falling edge of TCK.	
TMS	10R	Test mode select. This is the command input for the TAP controller state machine.	
TDI	11R	Test data input. This is the input side of the serial registers placed between TDI and TDO. The register placed between TDI and TDO is determined by the state of the TAP controller state machine and the instruction that is currently loaded in the TAP instruction.	
TDO	1R	Test data output. Output changes in response to the falling edge of TCK. This is the output side of the serial registers placed between TDI and TDO.	

Notes:

The device does not have TRST (TAP reset). The Test-Logic Reset state is entered while TMS is held high for five rising edges of TCK. The TAP controller state is also reset on SRAM POWER-UP.

TAP DC Operating Characteristics

```
(Ta = 0 \sim +70^{\circ}C @ R1Q*A****BG-**R** series)
(Ta = -40 \sim +85^{\circ}C @ R1Q*A****BG-**I** series)
(V<sub>DD</sub> = 1.8V \pm 0.1V)
```

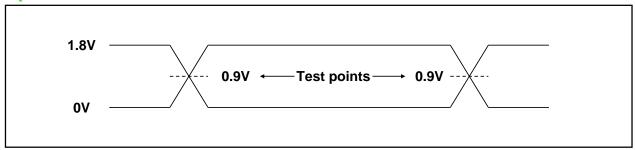
Parameter	Symbol	Min	Тур	Max	Unit	Notes
Input high voltage	V _{IH}	+1.3	_	$V_{DD} + 0.3$	٧	
Input low voltage	V _{IL}	-0.3	_	+0.5	٧	
Input leakage current	l _{LI}	-5.0		+5.0	μΑ	$0 \text{ V} \leq V_{IN} \leq V_{DD}$
Output leakage current	I _{LO}	-5.0		+5.0	μΑ	$ \begin{array}{c c} 0 \ V \leq V_{IN} \leq V_{DD}, \\ output \ disabled \end{array} $
Output low voltage	V _{OL1}			0.2	٧	$I_{OLC} = 100 \mu A$
Output low voltage	V_{OL2}	_		0.4	V	$I_{OLT} = 2 \text{ mA}$
Output high voltage	V _{OH1}	1.6	_	_	٧	$ I_{OHC} = 100 \mu A$
Output high voltage	V_{OH2}	1.4	_	_	V	$ I_{OHT} = 2 \text{ mA}$

- 1. All voltages referenced to V_{SS} (GND).
- 2. At power-up, V_{DD} and V_{DDQ} are assumed to be a linear ramp from 0V to V_{DD} (min.) or V_{DDQ} (min.) within 200ms. During this time $V_{DDQ} < V_{DD}$ and $V_{IH} < V_{DDQ}$. During normal operation, V_{DDQ} must not exceed V_{DD} .

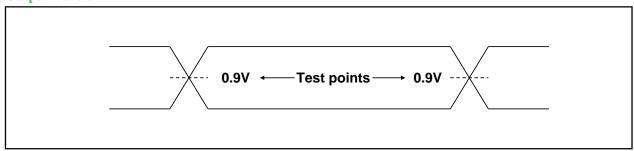
TAP AC Test Conditions

Parameter	Symbol	Conditions	Unit	Notes
Input timing measurement reference levels	V_{REF}	0.9	V	
Input pulse levels	V_{IL}, V_{IH}	0 to 1.8	V	
Input rise/fall time	tr, tf	≤ 1.0	ns	
Output timing measurement reference levels		0.9	V	
Test load termination supply voltage (V_{TT})		0.9	V	
Output load		See figures		

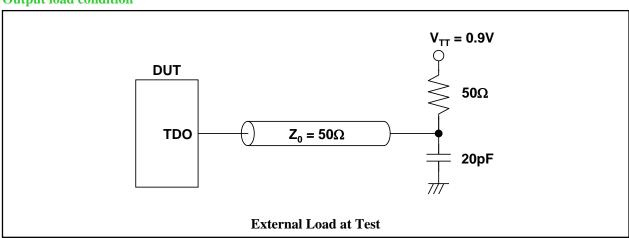
Input waveform



Output waveform



Output load condition



TAP AC Operating Characteristics

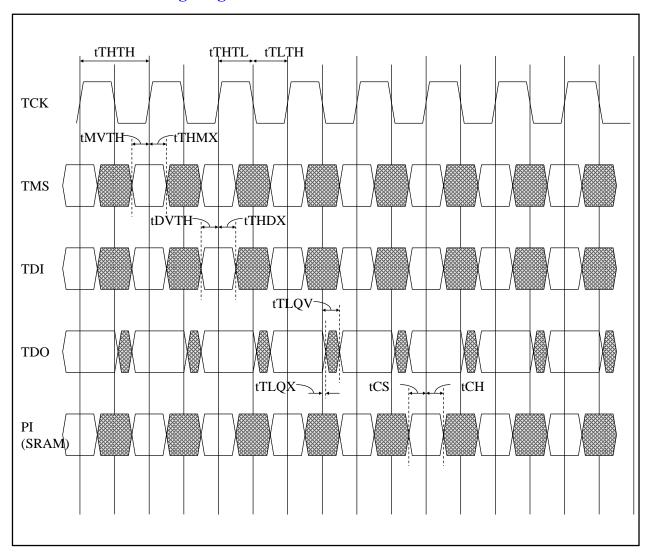
```
(Ta = 0 \sim +70^{\circ}C @ R1Q*A*****BG-**R** series)
(Ta = -40 ~ +85°C @ R1Q*A*****BG-**I** series)
(V<sub>DD</sub> = 1.8V ±0.1V)
```

Parameter	Symbol	Min	Тур	Max	Unit	Notes
Test clock (TCK) cycle time	t _{THTH}	50	_		ns	
TCK high pulse width	t _{THTL}	20			ns	
TCK low pulse width	t _{TLTH}	20			ns	
Test mode select (TMS) setup	t _{MVTH}	5			ns	
TMS hold	t _{THMX}	5			ns	
Capture setup	t _{cs}	5			ns	1
Capture hold	t _{CH}	5			ns	1
TDI valid to TCK high	t _{DVTH}	5		_	ns	
TCK high to TDI invalid	t _{THDX}	5		_	ns	
TCK low to TDO unknown	t _{TLQX}	0		_	ns	
TCK low to TDO valid	t_{TLQV}	_	_	10	ns	

Notes:

1. t_{CS} + t_{CH} defines the minimum pause in RAM I/O pad transitions to assure pad data capture.

TAP Controller Timing Diagram



Test Access Port Registers

Register name	Length	Symbol	Notes
Instruction register	3 bits	IR [2:0]	
Bypass register	1 bit	BP	
ID register	32 bits	ID [31:0]	
Boundary scan register	109 bits	BS [109:1]	

TAP Controller Instruction Set

at output balls are used to apply test vectors, while those at input balls capture test results. Typically, the first test vector is be applied using the EXTEST instruction will be shifted into the boundary scan register using the PRELOAD instruction. Thus during the Update-IR state of EXTEST, the output driver is turned on and the PRELOAD data is driven onto the output bit the ID register when the controller is in capture-DR mode and places the ID register between the TDI and TDO balls in shift-DR mode. The IDCODE instruction is the default instruction loaded in at power up and any time the controller is placed in the Test-Logic-Reset state. If the SAMPLE-Z instruction is loaded in the instruction register all RAM outputs are forced to an inactive drive state (high-Z), moving the TAP controller into the capture-DR state loads the data in the RAMs input into the boundary scan register, and the boundary scan register is connected between TDI and TDO when the TAP controller is moved to the shift-DR state. The RESERVED instructions are not implemented but are reserved for future use. Do not use these instructions register, moving the TAP controller into the capture-DR state loads the data in the RAMs input and I/O buffers into the boundary scan register. Because the RAM clock(s) are independent from the TAP clock (TCK) it is possible for the TAP to SAMPLE metastable input will not harm to attempt to capture the I/O ring contents while the input buffers are in transition (i.e., in a metastable state). Although allowing the TAP to SAMPLE metastable input will not harm to device, repeatable results cannot be expected. Moving the controller to shift-DR state then places the boundary scan register between the TDI and TDO balls.	IR2	IR1	IR0	Instruction	Description	Notes
the ID register when the controller is in capture-DR mode and places the ID register between the TDI and TDO balls in shift-DR mode. The IDCODE instruction is the default instruction loaded in at power up and any time the controller is placed in the Test-Logic-Reset state. If the SAMPLE-Z instruction is loaded in the instruction register all RAM outputs are forced to an inactive drive state (high-Z), moving the TAP controller into the capture-DR state loads the data in the RAMs input into the boundary scan register, and the boundary scan register is connected between TDI and TDO when the TAP controller is moved to the shift-DR state. The RESERVED instructions are not implemented but are reserved for future use. Do not use these instructions. When the SAMPLE instruction is loaded in the instruction register, moving the TAP controller into the capture-DR state loads the data in the RAMs input and I/O buffers into the boundary scan register. Because the RAM clock(s) are independent from the TAP clock (TCK) it is possible for the TAP to attempt to capture the I/O ring contents while the input buffers are in transition (i.e., in a metastable state). Although allowing the TAP to SAMPLE metastable input will not harm to device, repeatable results cannot be expected. Moving the controller to shift-DR state then places the boundary scan register between the TDI and TDO balls.	0	0	0	EXTEST	component package to be tested. Boundary scan register cells at output balls are used to apply test vectors, while those at input balls capture test results. Typically, the first test vector to be applied using the EXTEST instruction will be shifted into the boundary scan register using the PRELOAD instruction. Thus,	1, 2, 3, 5
all RAM outputs are forced to an inactive drive state (high-Z), moving the TAP controller into the capture-DR state loads the data in the RAMs input into the boundary scan register, and the boundary scan register is connected between TDI and TDO when the TAP controller is moved to the shift-DR state. The RESERVED instructions are not implemented but are reserved for future use. Do not use these instructions. When the SAMPLE instruction is loaded in the instruction register, moving the TAP controller into the capture-DR state loads the data in the RAMs input and I/O buffers into the boundary scan register. Because the RAM clock(s) are independent from the TAP clock (TCK) it is possible for the TAP controller into the capture the I/O ring contents while the input buffers are in transition (i.e., in a metastable state). Although allowing the TAP to SAMPLE metastable input will not harm to device, repeatable results cannot be expected. Moving the controller to shift-DR state then places the boundary scan register between the TDI and TDO balls. RESERVED RESERVED - RESERVED - RESERVED - Although allowing the TAP to SAMPLE metastable input will not harm to device, repeatable results cannot be expected. Moving the controller to shift-DR state then places the boundary scan register between the TDI and TDO balls.	0	0	1	IDCODE	loaded in at power up and any time the controller is placed in	
reserved for future use. Do not use these instructions. When the SAMPLE instruction is loaded in the instruction register, moving the TAP controller into the capture-DR state loads the data in the RAMs input and I/O buffers into the boundary scan register. Because the RAM clock(s) are independent from the TAP clock (TCK) it is possible for the TAP to attempt to capture the I/O ring contents while the input buffers are in transition (i.e., in a metastable state). Although allowing the TAP to SAMPLE metastable input will not harm to device, repeatable results cannot be expected. Moving the controller to shift-DR state then places the boundary scan register between the TDI and TDO balls. 1 0 1 RESERVED - 1 1 0 RESERVED - 1 1 0 RESERVED - - - - - - - - - - - - -	0	1	0	SAMPLE-Z	moving the TAP controller into the capture-DR state loads the data in the RAMs input into the boundary scan register, and the boundary scan register is connected between TDI and TDO	3, 4, 5
register, moving the TAP controller into the capture-DR state loads the data in the RAMs input and I/O buffers into the boundary scan register. Because the RAM clock(s) are independent from the TAP clock (TCK) it is possible for the TA to attempt to capture the I/O ring contents while the input buffers are in transition (i.e., in a metastable state). Although allowing the TAP to SAMPLE metastable input will not harm to device, repeatable results cannot be expected. Moving the controller to shift-DR state then places the boundary scan register between the TDI and TDO balls. 1 0 1 RESERVED	0	1	1	RESERVED	·	
1 1 0 RESERVED -	1	0	0		register, moving the TAP controller into the capture-DR state loads the data in the RAMs input and I/O buffers into the boundary scan register. Because the RAM clock(s) are independent from the TAP clock (TCK) it is possible for the TAP to attempt to capture the I/O ring contents while the input buffers are in transition (i.e., in a metastable state). Although allowing the TAP to SAMPLE metastable input will not harm the device, repeatable results cannot be expected. Moving the controller to shift-DR state then places the boundary scan	3, 5
	1	0	1	RESERVED	•	
The BYPASS instruction is loaded in the instruction register	1	1	0	RESERVED	-	
when the bypass register is placed between TDI and TDO. T	1	1	1	BYPASS	·	

- 1. Data in output register is not guaranteed if EXTEST instruction is loaded.
- 2. After performing EXTEST, power-up conditions are required in order to return part to normal operation.
- 3. RAM input signals must be stabilized for long enough to meet the TAPs input data capture setup plus hold time (t_{CS} plus t_{CH}). The RAMs clock inputs need not be paused for any other TAP operation except capturing the I/O ring contents into the boundary scan register.
- 4. Clock recovery initialization cycles are required after boundary scan.
- 5. For R1QD, R1QE, R1QF, R1QK, R1QL, R1QM, R1QP series, ODT is disabled in EXTEST, SAMPLE-Z or SAMPLE mode.

Boundary Scan Order

D:/ #	D. II ID.	S	ignal name	s	D:/ //	D. II ID	S	ignal name	es .
Bit #	Ball ID	х9	x18	x36	Bit #	Ball ID	х9	x18	x36
1	6R	/C or NC or ODT	/C or NC or ODT	/C or NC or ODT	36	10E	D3	D6	D6
2	6P	C or QVLD	C or QVLD	C or QVLD	37	10D	NC	NC	D15
3	6N	SA	SA	SA	38	9E	NC	NC	Q15
4	7P	SA	SA	SA	39	10C	NC	Q7	Q7
5	7N	SA	SA	SA	40	11D	NC	D7	D7
6	7R	SA	SA	SA	41	9C	NC	NC	D16
7	8R	SA	SA	SA	42	9D	NC	NC	Q16
8	8P	SA	SA	SA	43	11B	Q4	Q8	Q8
9	9R	SA	SA	SA	44	11C	D4	D8	D8
10	11P	Q0	Q0	Q0	45	9B	NC	NC	D17
11	10P	D0	D0	D0	46	10B	NC	NC	Q17
12	10N	NC	NC	D9	47	11A	CQ	CQ	CQ
13	9P	NC	NC	Q9	48	10A	SA	NC	NC
14	10M	NC	Q1	Q1	49	9A	SA	SA	SA
15	11N	NC	D1	D1	50	8B	SA	SA	SA
16	9M	NC	NC	D10	51	7C	SA	SA	SA
17	9N	NC	NC	Q10	52	6C	NC	NC	NC
18	11L	Q1	Q2	Q2	53	8A	/R	/R	/R
19	11M	D1	D2	D2	54	7A	NC	NC	/BW1
20	9L	NC	NC	D11	55	7B	/BW	/BW0	/BW0
21	10L	NC	NC	Q11	56	6B	K	K	K
22	11K	NC	Q3	Q3	57	6A	/K	/K	/K
23	10K	NC	D3	D3	58	5B	NC	NC	/BW3
24	9J	NC	NC	D12	59	5A	NC	/BW1	/BW2
25	9K	NC	NC	Q12	60	4A	/W	/W	/W
26	10J	Q2	Q4	Q4	61	5C	SA	SA	SA
27	11J	D2	D4	D4	62	4B	SA	SA	SA
28	11H	ZQ	ZQ	ZQ	63	3A	SA	SA	NC
29	10G	NC	NC	D13	64	2A	NC	NC	NC
30	9G	NC	NC	Q13	65	1A	/CQ	/CQ	/CQ
31	11F	NC	Q5	Q5	66	2B	NC	Q9	Q18
32	11G	NC	D5	D5	67	3B	NC	D9	D18
33	9F	NC	NC	D14	68	1C	NC	NC	D27
34	10F	NC	NC	Q14	69	1B	NC	NC	Q27
35	11E	Q3	Q6	Q6	70	3D	NC	Q10	Q19

Boundary Scan Order

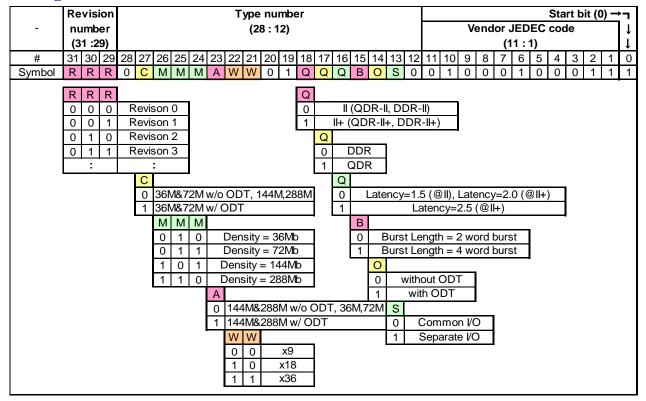
D:4 #	Dell ID	S	ignal name	es .	D:4 #	Dell ID	S	ignal name	es
Bit #	Ball ID	x9	x18	x36	Bit #	Ball ID	x9	x18	x36
71	3C	NC	D10	D19	91	2L	Q7	Q15	Q24
72	1D	NC	NC	D28	92	3L	D7	D15	D24
73	2C	NC	NC	Q28	93	1M	NC	NC	D33
74	3E	Q5	Q11	Q20	94	1L	NC	NC	Q33
75	2D	D5	D11	D20	95	3N	NC	Q16	Q25
76	2E	NC	NC	D29	96	3M	NC	D16	D25
77	1E	NC	NC	Q29	97	1N	NC	NC	D34
78	2F	NC	Q12	Q21	98	2M	NC	NC	Q34
79	3F	NC	D12	D21	99	3P	Q8	Q17	Q26
80	1G	NC	NC	D30	100	2N	D8	D17	D26
81	1F	NC	NC	Q30	101	2P	NC	NC	D35
82	3G	Q6	Q13	Q22	102	1P	NC	NC	Q35
83	2G	D6	D13	D22	103	3R	SA	SA	SA
84	1H	/DOFF	/DOFF	/DOFF	104	4R	SA	SA	SA
85	1J	NC	NC	D31	105	4P	SA	SA	SA
86	2J	NC	NC	Q31	106	5P	SA	SA	SA
87	3K	NC	Q14	Q23	107	5N	SA	SA	SA
88	3J	NC	D14	D23	108	5R	SA	SA	SA
89	2K	NC	NC	D32	109		INTER- NAL	INTER- NAL	INTER- NAL
90	1K	NC	NC	Q32		_	_	_	_

Notes:

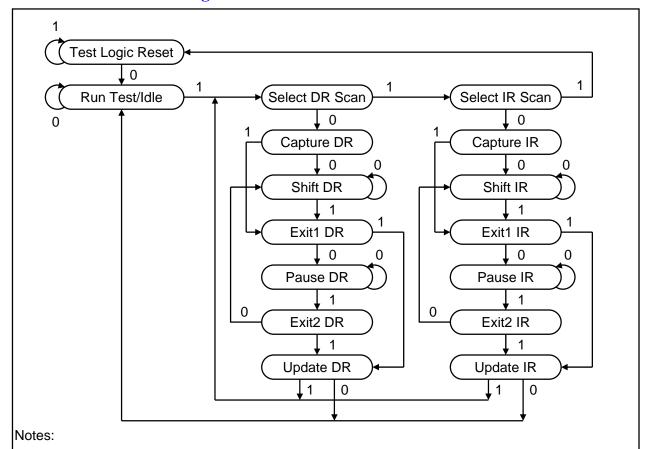
In boundary scan mode,

- 1. Clock balls (K, /K, C, /C) are referenced to each other and must be at opposite logic levels for reliable operation.
- 2. CQ and /CQ data are synchronized to the respective C and /C (except EXTEST, SAMPLE-Z).
- 3. If C and /C tied high, CQ is generated with respect to K and /CQ is generated with respect to /K (except EXTEST, SAMPLE-Z).

ID Register



TAP Controller State Diagram



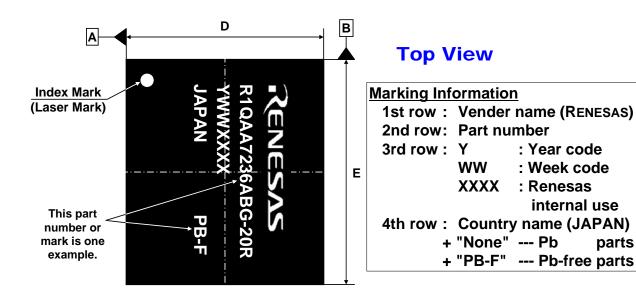
The value adjacent to each state transition in this figure represents the signal present at TMS at the time of a rising edge at TCK.

No matter what the original state of the controller, it will enter Test-Logic-Reset when TMS is held high for at least five rising edges of TCK.

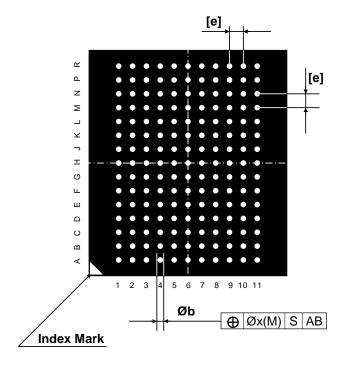
Package Dimensions and Marking Information

Both Pb parts and Pb-free parts are available.

JEITA Package Code	Renesas Code	Previous Code	Mass (typ.)
P-LBGA165-15x17-1.00	PLBG0165FD-A	165FHE	0.6 g







Bottom View

Reference	Dimer	nsion i	n mm
Symbol	Min	Nom	Max
D	14.9	15.0	15.1
Е	16.9	17.0	17.1
Α	-	-	1.4
A1	0.27	0.32	0.37
[e]	-	1.0	-
b	0.45	0.5	0.55
Х	-	-	0.2
у	-	-	0.15

parts

Revision History (1)

Rev.	Date	#	Comment
Rev. 0. 00a	' 08. 10. 08	1	Initial issue.
Rev. 0. 00b	' 08. 10. 09	1	Corrected typos in "DC Characteristics": VOH/VOL= VDDQ/2±1.12 → ±0.12.
		4	Added "Speed Bin Table".
Rev. 0. 00c	'08.11.19	1	Added "ODT timing chart" to QDRII+ and DDRII+ series.
		1	Corrected typos in "General Description": ODT pin = Q0∼Qn → D0∼Dn.
Rev. 0. 00d	, 00 11 20	7	Updated "Recommended DC Operating Conditions": Vref =0.68∼0.95V → 0.7∼
Kev. U. UUU	00.11.20		O. 8V (II+ series).
		3	Added comment to "Thermal Resistance" section: These are reference values.
Rev. 0. 00e	'08.12.07	1	Added "Generation Number Table".
		1	Changed Marking Name in "Part Number Definition Table".
	0. 00 f , 09. 02. 09		
Rev. 0. 00 f		2	Added marking information to "Package Dimension Information" section.
-1	09. 02. 09	3	Corrected ODT On/Off timing in "ODT pin" table.
		4	Updated minimum frequency of QDRII+ and DDRII+ series.
			Changed pin name in "Pin Arrangement" of DDRII+ series: SAO/SA1 → NC.
		6	Added the row to "K Truth Table": RL=2.0 and RL=2.5.
Rev. 0. 00g	' 09. 02. 24		Updated SET-UP cycles: II+ series DLL lock time = 20us → 2048 cycle. Added comment to "ODT on/off Timing Chart" section: ODT on/off switching
-1		2	timings are edge aligned with CQ or /CQ.
'		3	Updated "Thermal Resistance".
Rev. 0. 00h	' N	1	Added "-50" speed bin to QDR II B2 x18/x36 series.
		i	Updated "Package Dimensions": Mass=0.7→0.6g, A(max)=1.46→1.4mm.
Rev. 0. 00 i	'09.06.15	2	Updated "Operating/Standby Supply Currents".
		-	Added comment to "Power-up and Initialization Sequence" section: Apply Vref
Rev. 0. 01a	'09.10.25	1	after Vddq or at the same time as Vddq.
		2	Updated "Speed Bin Table".
		1	Added "Renesas QDR SRAM Homepage URL" to notes of front page.
		2	Updated "Power-up and Initialization Sequence".
Rev. 0. 02a	, 10 02 01	3	Updated "DLL Constraints".
1 KGV. 0. 024	10. 02. 01	4	Updated "Operating Supply Current" and "Standby Supply Current"
		5	Updated "Thermal Resistance".
		6	Changed remarks of "AC Characteristics" on "Control signals".
		1	Changed company name, RENESAS logo and base color from those of Renesas
Rev. 0. 03a	10 04 01		Technology to Renesas Electronics. Changed vender name marking in "Package Dimensions and Marking Information"
Nev. U. UJa	10.04.01	2	Isection.
		3	Added "A" generation to 72M series.
			Changed the pin description for NC pin.
Rev. N. N4a	' 10. 06. 10		Changed note 4 of "TAP Controller Instruction Set": "Clock recovery
		2	initialization cycles are required after boundary scan"
		1	Changed Vddq range of II+ series: Vddq=1.5±0.1V → 1.4V ~ Vdd.
Rev. 0. 05a	' 10. 06. 25	2	Added Note.8 and Note.9 to AC Characteristics table for II+ series.
		3	Updated Speed Bin Table for 144M.
Rev. 0. 05b	' 10. 07. 02	1	Added Note.2 to Generation Number Table.
NG V. U. UUU	10.07.02	2	Updated Speed Bin Table for 36M and 72M.
Rev. 0. 05c	' 10. 07. 24	1	Updated Operating Supply Current and Standby Supply Current Table for 36M
1.01. 0. 000	10.07.27		and 72M.
Rev. 0. 06a	' 10. 09. 20	1	Changed Initialization Sequence: Initial cycle of II+ series = 2048cycles
		1	→ 20us.
Rev. 0. 07a	' 10. 10. 06	1	Added Note. 9 to AC Characteristics table for 11 series.
	'10.10.30	1 2	Updated AC Characteristics for the series of RL=2.0.
Rev. 0. 07b		2	Updated Speed Bin Table for 72M/36M/144M. Added R1QNA, R1QPA series to 144M QDR lineup.
		J	Changed JTAG/ID Register (ID Code):
			#27="0": 36M&72M w/o ODT, 144M, 288M
			"1": 36M&72M w/ ODT
		4	#23="0": 144M&288M w/o ODT, 36M, 72M
			"1": 144M&288M w/ ODT
			$\#(26, 25, 24) = \text{``100''} \rightarrow \text{``101''} (144M), \text{``101''} \rightarrow \text{``110''} (288M).$
			11 (-0; -0; -1, 100 101 (111m/) 101 110 (200m/)

Revision History (2)

Rev.	Date	#	Comment
Rev. 0. 08a	' 11. 05. 23	1	Added Note.7 to tQVLD in AC Characteristics table for II+ series.
			Changed description of tQVLD in AC Characteristics table for RL=2 series: CQ high to QVLD valid → /CQ high to QVLD valid.
		3	Updated Remarks 4 of AC Characteristics table.
		4	Updated tKHKH(max) in AC Characteristics table for QDRII+ B2 series.
		5	Added 13 x15 mm package lineup to 36M ll+ & 72M ll/ll+ series.
		6	Copyright: (c)2010 → (c)2011

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