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# MOS INTEGRATED CIRCUIT $\mu$ PD4711B

## RS-232 LINE DRIVER/RECEIVER

The  $\mu$ PD4711B is a high-voltage silicon gate CMOS line driver/reciever conforming to the EIA/TIA-232-E standard. It can operate with a single +5 V power source because it is provided with a DC-DC converter. In addition, this line driver/receiver has many ancillary functions, including output control, threshold select, and standby functions. Because the  $\mu$ PD4711B is provided with two output driver circuits and two receiver circuits, it can constitute an RS-232 interface circuit with a single chip.

#### **FEATURES**

- Conforms to EIA/TIA-232-E (RS-232C) standard
- +5 V single power source
- Threshold select pin selecting two types of threshold voltages
- Standby mode can be set by making standby pin high to reduce circuit current.
- Three-state output configuration. Both driver and receiver outputs go into high-impedance state in standby mode.

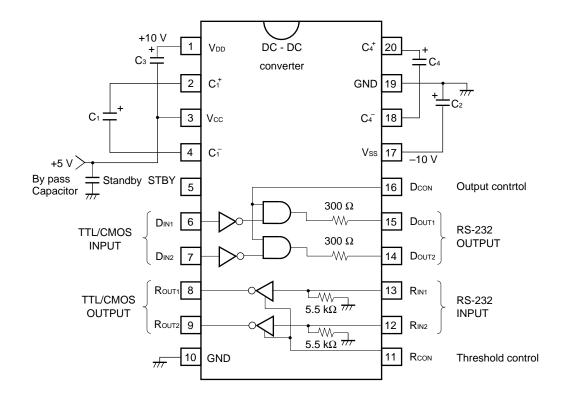
#### ORDERING INFORMATION

Part Number	Package	
μPD4711BCX	20-pin plastic DIP (300 mil)	
μPD4711BGS	20-pin plastic SOP (300 mil)	

The information in this document is subject to change without notice.



# **BLOCK DIAGRAM/PIN CONFIGURATION (Top View)**



- \* V<sub>DD</sub> and V<sub>ss</sub> are output pins of voltages internally boosted. Connecting a load directly to these pins is not recommended.
- \*\* The standby pin is internally pulled down.
- \*\*\* Use capacitors with a working voltage of 16 V or higher as C<sub>1</sub> through C<sub>4</sub>. Insert a bypass capasitor about 0.1 to 1 μF between Vcc pin to GND pin.



# TRUTH TABLE

# **Drivers**

STBY	Dcon	Din	<b>D</b> оит	Remark
Н	Х	Х	Z	Standby mode (DC-DC converter stops)
L	L	Х	L	Mark level output
L	Н	L	Н	Space level output
L	Н	Н	L	Mark level output

# Receivers

STBY	Rin	Rоит	Remark
Н	Х	Z	Stanby mode (DC-DC converter stops)
L	L	Н	Mark level input
L	Н	L	Space level input

# Receiver input threshold voltage

Rcon	RIN1 to RIN2
L	A mode
Н	B mode

H: high level, L: low level, Z: high impedance, X: H or L



# ABSOLUTE MAXIMUM RATINGS $(T_A = 25 \degree C)$

Parameter	Symbol	Ratings	Unit
Supply voltage	Vcc	-0.5 to +6.0	V
Driver input voltage	Din	−0.5 to Vcc +0.5	V
Receiver input voltage	Rın	-30.0 to +30.0	V
Driver output voltage	<b>D</b> оит	−25.0 to +25.0 <sup>Note 1</sup>	V
Receiver output voltage	Rоит	-0.5 to Vcc + 0.5	V
Receiver input current	lin	±60.0	mA
Operating temperature range	TA	-40 to +85	°C
Storage temperature range	T <sub>stg</sub>	-55 to +150	°C
Power dissipation	Рт	0.5	W

Note 1. Pulse width: 1 ms, duty factor: 10 % MAX.

# RECOMMENDED OPERATING RANGE

Parameter	Symbol	MIN.	TYP.	MAX.	Unit
Supply voltage	Vcc	4.5	5.0	5.5	V
Receiver input voltage	Rin	-30		+30	V
Operating temperature range	TA	-20		80	°C
External capacitance	Note 2	1.0	22	47	μF

**Note 2.** The capacitance of an electrolytic capacitor decreases at a low temperature (0  $^{\circ}$ C or lower). Determine the capacitance of the capacitor to be used taking this into consideration when the  $\mu$ PD4711B is used at a low temperature. Keep the wiring length between the capacitor and IC as short as possible.

# ELECTRICAL CHARACTERISTICS (OVERALL) (Unless otherwise specified, Vcc = +5 V $\pm 10$ %, T<sub>A</sub> = -20 °C to +80 °C, C<sub>1</sub> to C<sub>4</sub> = 22 $\mu$ F)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Circuit current		Vcc = +5 V, no load, R <sub>IN</sub> pin open				
	Icc1	(Standby pin open)		4.5	9.0	mA
Circuit current		$Vcc$ = +5 $V$ , $RL$ = 3 $k\Omega$ (Dout), $DIN$ = $GND$ ,				
	Icc2	RIN and ROUT pins open		15.0	25.0	mA
		(Standby pin open)				
Standby circuit current	Icc	Vcc = +5 V, no load, R <sub>IN</sub> pin open			400	
	(Standby)	(Standby pin high)		50	120	μΑ
Standby low-level	VIL	Note 3				
input voltage	(Standby)				0.8	V
Standby high-level	Vih					
input voltage	(Standby)		2.0			V
Input capacitance	Cin	Driver input and receiver input				
		Vcc = +5 V, vs. GND, f = 1 MHz			10	pF

<sup>\*</sup> TYP.: Typical (reference) value at  $T_A = 25$  °C.

Note 3. Because the standby pin is internally pulled down, if the standby pin is left open, operating mode is in effect.



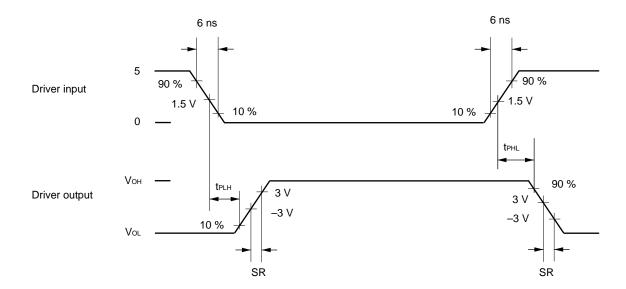
# ELECTRICAL CHARACTERISTICS (DRIVER) (Unless otherwise specified, Vcc = +5 V $\pm 10$ %, T<sub>A</sub> = -20 °C to +80 °C, C<sub>1</sub> to C4 = 22 $\mu$ F)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Low-level input voltage	VıL				0.8	V
High-level input voltage	Vıн		2.0			V
Low-level input current	lı∟		0		-1.0	μΑ
High-level input current	Іін		0		1.0	μΑ
Output voltage		Vcc = +5.0 V, R <sub>L</sub> = ∞, T <sub>A</sub> = 25 °C		±9.7		V
	VDO	$Vcc = +5.0 \text{ V}, \text{ RL} = 3 \text{ k}\Omega$	±5.5			V
		$Vcc = +4.5 \text{ V}, \text{ RL} = 3 \text{ k}\Omega$	±5.0			V
Output short current	Isc	Vcc = +5.0 V, vs. GND		±15	±40	mA
Slew rate		$C_L = 10 \text{ pF}, R_L = 3 \text{ to } 7 \text{ k}\Omega$	1.5	11	30	V/μs
	SR	$C_L$ = 2500 pF, $R_L$ = 3 to 7 k $\Omega$	1.5	6	30	V/μs
Propagation delay timeNote 4	<b>t</b> PHL					
	<b>t</b> PLH	$R_L = 3.5 \text{ k}\Omega, C_L = 2500 \text{ pF}$		0.8		μs
Output resistance		Vcc = Vdd = Vss = 0 V				
	Ro	Vоит = ±2 V	300			Ω
Standby output transition time	<b>t</b> DAZ	Note 5		4	10	μs
Standby output transition time	<b>t</b> dza	Note 5		25	50	ms

<sup>\*</sup> TYP.: Typical (reference) value at  $T_A = 25$  °C.

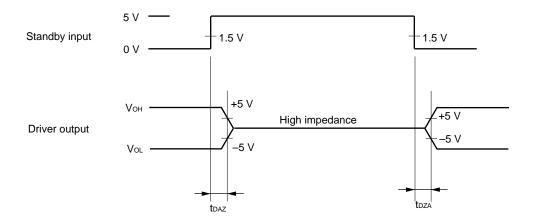
# Note 4. Test point

If the output control pin is made low, the driver output goes low regardless of the driver input state.





Note 5. Test Point



Do not perform communication within the standby output transition time t<sub>DZA</sub> on power application or on releasing the standby mode.

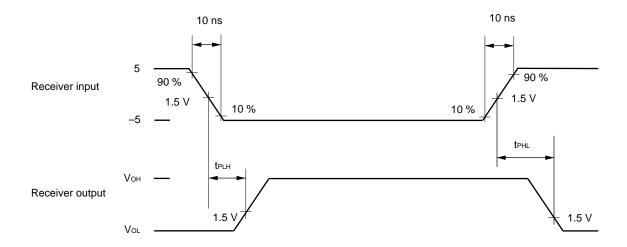
# ELECTRICAL CHARACTERISTICS (RECEIVER) (Unless otherwise specified, Vcc = +5 V $\pm$ 10 %, T<sub>A</sub> = -20 °C to +80 °C, C<sub>1</sub> to C<sub>4</sub> = 22 $\mu$ F)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Low-level output voltage	Vol	Іоит = 4 mA			0.4	V
High-level output voltage	V	IOUT = −4 mA	Vcc			V
	Vон	IOUT = -4 MA	-0.8			V
Low-level input voltage	VIL	Rcon pin			0.8	V
High-level input voltage	ViH	RCON pin	2.0			V
Propagation delay timeNote 6	<b>t</b> PHL	D 410 C 450 F		0.40		
	tplH	$R_L = 1 \text{ k}\Omega$ , $C_L = 150 \text{ pF}$		0.13		μs
Input current	lin	V <sub>IN</sub> = ±5 V		1		mA
Input resistance	Rı	$V_{IN} = \pm 3 \text{ to } \pm 25$	3	5	7	kΩ
Input pin release voltage	Vio	Input threshold A mode only			0.5	V
Input threshold A mode	ViH	Vcc = +5 V	1.6	2.2	2.6	V
(Rcon pin low)	VIL	Vcc = +5 V	0.6	1	1.6	V
	Vн	Vcc = +5 V (hysteresis width)	0.5	1.2	1.8	V
Input threshold B mode	ViH	Vcc = +5 V	1.6	2.2	2.6	V
(Rcon pin high)	VIL	Vcc = +5 V	-0.4	-1.8	-3.0	V
	Vн	Vcc = +5 V (hysteresis width)	2.6	4.0	5.4	V
Standby output transition time	<b>t</b> DAZ	Note 7		0.4	1	μs
Standby output transition time	<b>t</b> DZA	Note 7		0.03	10	ms

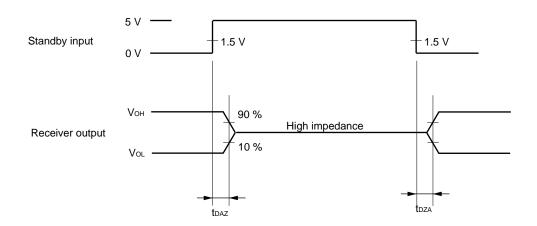
<sup>\*</sup> TYP.: Typical (reference) value at  $T_A = 25$  °C.



Note 6. Test Point



Note 7. Test Point

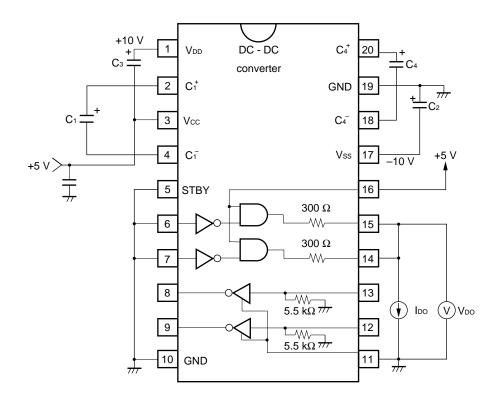


The receiver output is undefined during the standby output transition time toza. Do not perform communication in the standby output transition time toza on power application or on releasing the standby mode.

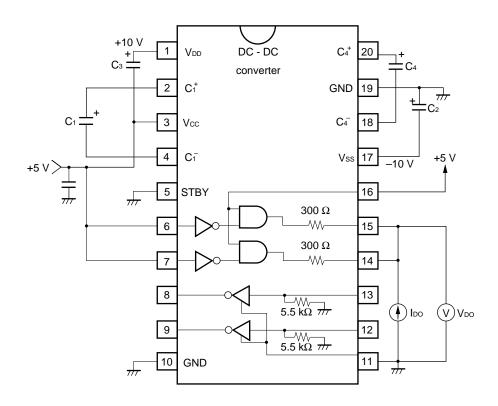


**TEST CIRCUIT** 

# Driver output voltage/Output current (+ side)

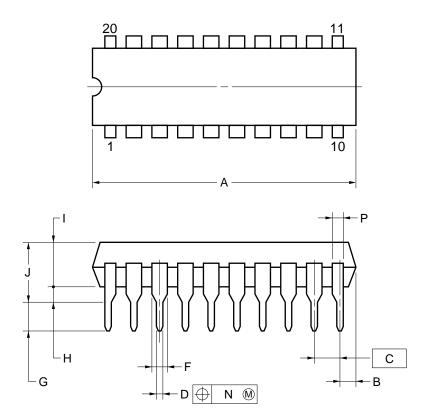


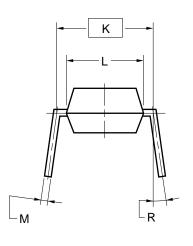
# Driver output voltage/Output current (- side)



# **PACKAGE DRAWINGS**

# 20PIN PLASTIC DIP (300 mil)





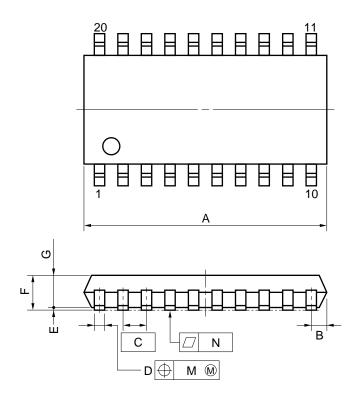
#### **NOTES**

- 1) Each lead centerline is located within 0.25 mm (0.01 inch) of its true position (T.P.) at maximum material condition.
- 2) Item "K" to center of leads when formed parallel.

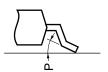
ITEM	MILLIMETERS	INCHES
Α	25.40 MAX.	1.000 MAX.
В	1.27 MAX.	0.050 MAX.
С	2.54 (T.P.)	0.100 (T.P.)
D	0.50±0.10	$0.020^{+0.004}_{-0.005}$
F	1.1 MIN.	0.043 MIN.
G	3.5±0.3	0.138±0.012
Н	0.51 MIN.	0.020 MIN.
I	4.31 MAX.	0.170 MAX.
J	5.08 MAX.	0.200 MAX.
K	7.62 (T.P.)	0.300 (T.P.)
L	6.4	0.252
М	0.25 <sup>+0.10</sup> -0.05	0.010+0.004
N	0.25	0.01
Р	0.9 MIN.	0.035 MIN.
R	0~15°	0~15°

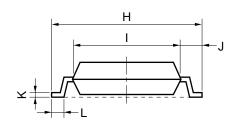
P20C-100-300A,C-1

# 20 PIN PLASTIC SOP (300 mil)



# detail of lead end





### NOTE

Each lead centerline is located within 0.12 mm (0.005 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES
Α	13.00 MAX.	0.512 MAX.
В	0.78 MAX.	0.031 MAX.
С	1.27 (T.P.)	0.050 (T.P.)
D	$0.40^{+0.10}_{-0.05}$	$0.016^{+0.004}_{-0.003}$
Е	0.1±0.1	0.004±0.004
F	1.8 MAX.	0.071 MAX.
G	1.55	0.061
Н	7.7±0.3	0.303±0.012
ı	5.6	0.220
J	1.1	0.043
K	$0.20^{+0.10}_{-0.05}$	$0.008^{+0.004}_{-0.002}$
L	0.6±0.2	0.024+0.008
М	0.12	0.005
N	0.10	0.004
Р	3°+7°	3°+7°

P20GM-50-300B, C-4



#### RECOMMENDED SOLDERING CONDITIONS

Soldering the  $\mu$ PD4711B under the conditions listed in the table below is recommended.

For soldering methods and conditions other than those recommended, consult NEC.

#### Surface mount type

For the details of the recommended soldering conditions of the surface mount type, refer to Information document "Semiconductor Device Mounting Technology Manual" C10535EJ7V0IF00.

## $\mu$ PD4711BGS

Soldering Method	Soldering Condition	Recommended Condition Symbol
Infrared reflow	Package peak temperature: 235 °C, Time: 30 seconds MAX.	IR35-00-2
	(210 °C MIN.), Number of times: 2, Number of days: not limited*	
VPS	Package peak temperature: 215 °C, Time: 40 seconds MAX.	VP15-00-2
	(200 °C MIN.), Number of times: 2, Number of days: not limited*	
Wave soldering	Soldering bath temperature: 260 °C MAX., Time: 10 seconds	WS60-00-1
	MAX., Number of times: 1, Number of days: not limited*	
Pin partial heating	Pin temperature: 300 °C MAX (lead temperature), Time: 3	
	seconds MAX. (per lead pin), Number of days: not	
	limited*	

<sup>\*</sup> The number of days the device can be stored at 25 °C, 65 % RH MAX. after the dry pack has been opened.

Caution Do not use two or more soldering methods in combination (except the pin partial heating method).

# Throught-hole type

# $\mu$ PD4711BCX

Soldering Method	Soldering Conditions
Wave soldering	Soldering bath temperature: 260 °C MAX., Time: 10 seconds MAX.

#### Reference documents

"NEC Semiconductor Device Reliability/Quality Control System" (IEI-1212)

"Quality Grade on NEC Semiconductor Devices" (IEI-1209)

"Semiconductor Device Mounting Technology Manual" C10535EJ7V0IF00

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Special: Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support)

Specific: Aircrafts, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems or medical equipment for life support, etc.

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Anti-radioactive design is not implemented in this product.

M4 96.5