

## Rochester Electronics Manufactured Components

Rochester branded components are manufactured using either die/wafers purchased from the original suppliers or Rochester wafers recreated from the original IP. All recreations are done with the approval of the OCM.

Parts are tested using original factory test programs or Rochester developed test solutions to guarantee product meets or exceed the OCM data sheet.

### **Quality Overview**

- ISO-9001
- AS9120 certification
- Qualified Manufacturers List (QML) MIL-PRF-35835
  - Class Q Military
  - Class V Space Level
- Qualified Suppliers List of Distributors (QSLD)
- Rochester is a critical supplier to DLA and meets all industry and DLA standards.

Rochester Electronics, LLC is committed to supplying products that satisfy customer expectations for quality and are equal to those originally supplied by industry manufacturers.

The original manufacturer's datasheet accompanying this document reflects the performance and specifications of the Rochester manufactured version of this device. Rochester Electronics guarantees the performance of its semiconductor products to the original OEM specifications. 'Typical' values are for reference purposes only. Certain minimum or maximum ratings may be based on product characterization, design, simulation, or sample testing.

## **BCD Decade Counters/ 4-Bit Binary Counters**

The LS161A/163A are high-speed 4-bit synchronous counters. They are edge-triggered, synchronously presettable, and cascadable MSI building blocks for counting, memory addressing, frequency division and other applications. The LS161A and LS163A count modulo 16 (binary).

The LS161A has an asynchronous Master Reset (Clear) input that overrides, and is independent of, the clock and all other control inputs. The LS163A has a Synchronous Reset (Clear) input that overrides all other control inputs, but is active only during the rising clock edge.

	Binary (Modulo 16)		
Asynchronous Reset	LS161A		
Synchronous Reset	LS163A		

- Synchronous Counting and Loading
- Two Count Enable Inputs for High Speed Synchronous Expansion
- Terminal Count Fully Decoded
- Edge-Triggered Operation
- Typical Count Rate of 35 MHz
- ESD > 3500 Volts

#### **GUARANTEED OPERATING RANGES**

Symbol	Parameter	Min	Тур	Max	Unit
VCC	Supply Voltage	4.75	5.0	5.25	V
T <sub>A</sub>	Operating Ambient Temperature Range	0	25	70	°C
IOH	Output Current – High			-0.4	mA
lOL	Output Current – Low			8.0	mA



#### ON Semiconductor™

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# LOW POWER SCHOTTKY



PLASTIC N SUFFIX CASE 648



SOIC D SUFFIX CASE 751B



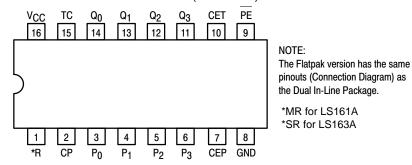
SOEIAJ M SUFFIX CASE 966

#### **ORDERING INFORMATION**

Device	Package	Shipping
SN74LS161AN	16 Pin DIP	2000 Units/Box
SN74LS161AD	SOIC-16	38 Units/Rail
SN74LS161ADR2	SOIC-16	2500/Tape & Reel
SN74LS161AM	SOEIAJ-16	See Note 1
SN74LS161AMEL	SOEIAJ-16	See Note 1
SN74LS163AN	16 Pin DIP	2000 Units/Box
SN74LS163AD	SOIC-16	38 Units/Rail
SN74LS163ADR2	SOIC-16	2500/Tape & Reel
SN74LS163AM	SOEIAJ-16	See Note 1
SN74LS163AMEL	SOEIAJ-16	See Note 1

For ordering information on the EIAJ version of the SOIC package, please contact your local ON Semiconductor representative.

#### **CONNECTION DIAGRAM DIP (TOP VIEW)**



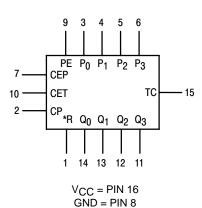
LOADING	(Note	a١
LOADINO	UNOIC	u

PIN NAMES		HIGH	LOW
PE	Parallel Enable (Active LOW) Input	1.0 U.L.	0.5 U.L.
P <sub>0</sub> - P <sub>3</sub>	Parallel Inputs	0.5 U.L.	0.25 U.L.
CEP	Count Enable Parallel Input	0.5 U.L.	0.25 U.L.
CET	Count Enable Trickle Input	1.0 U.L.	0.5 U.L.
<u>CP</u>	Clock (Active HIGH Going Edge) Input	0.5 U.L.	0.25 U.L.
MR	Master Reset (Active LOW) Input	0.5 U.L.	0.25 U.L.
SR	Synchronous Reset (Active LOW) Input	1.0 U.L.	0.5 U.L.
Q <sub>0</sub> - Q <sub>3</sub>	Parallel Outputs	10 U.L.	5 U.L.
TC	Terminal Count Output	10 U.L.	5 U.L.

#### NOTES:

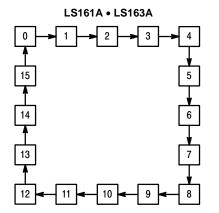
a) 1 TTL Unit Load (U.L.) = 40  $\mu$ A HIGH/1.6 mA LOW.

#### **LOGIC SYMBOL**



\*MR for LS161A

#### STATE DIAGRAM



#### **LOGIC EQUATIONS**

Count Enable = CEP • CET • PE
TC for LS161A & LS163A = CET •  $Q_0$  •  $Q_1$  •  $Q_2$  •  $Q_3$ Preset = PE • CP + (rising clock edge)
Reset = MR (LS161A)
Reset = SR • CP + (rising clock edge)
(LS163A)

#### **FUNCTIONAL DESCRIPTION**

The LS161A/163A are 4-bit synchronous counters with a synchronous Parallel Enable (Load) feature. The counters consist of four edge-triggered D flip-flops with the appropriate data routing networks feeding the D inputs. All changes of the Q outputs (except due to the asynchronous Master Reset in the LS161A) occur as a result of, and synchronous with, the LOW to HIGH transition of the Clock input (CP). As long as the set-up time requirements are met, there are no special timing or activity constraints on any of the mode control or data inputs.

Three control inputs — Parallel Enable (PE), Count Enable Parallel (CEP) and Count Enable Trickle (CET) — select the mode of operation as shown in the tables below. The Count Mode is enabled when the CEP, CET, and PE inputs are HIGH. When the PE is LOW, the counters will synchronously load the data from the parallel inputs into the flip-flops on the LOW to HIGH transition of the clock. Either the CEP or CET can be used to inhibit the count sequence. With the PE held HIGH, a LOW on either the CEP or CET inputs at least one set-up time prior to the LOW to HIGH clock transition will cause the existing output states to be retained. The AND feature of the two Count Enable inputs (CET•CEP) allows synchronous cascading without external gating and without delay accumulation over any practical number of bits or digits.

The Terminal Count (TC) output is HIGH when the Count Enable Trickle (CET) input is HIGH while the counter is in its maximum count state (HLLH for the BCD counters, HHHH for the Binary counters). Note that TC is fully decoded and will, therefore, be HIGH only for one count state.

The LS161A and LS163A count modulo 16 following a binary sequence. They generate a TC when the CET input is HIGH while the counter is in state 15 (HHHH). From this state they increment to state 0 (LLLL).

The Master Reset (MR) of the LS161A is asynchronous. When the MR is LOW, it overrides all other input conditions and sets the outputs LOW. The MR pin should never be left open. If not used, the MR pin should be tied through a resistor to  $V_{CC}$ , or to a gate output which is permanently set to a HIGH logic level.

The active LOW Synchronous Reset (SR) input of the LS163A acts as an edge-triggered control input, overriding CET, CEP and PE, and resetting the four counter flip-flops on the LOW to HIGH transition of the clock. This simplifies the design from race-free logic controlled reset circuits, e.g., to reset the counter synchronously after reaching a predetermined value.

#### **MODE SELECT TABLE**

*SR	PE	CET	CEP	Action on the Rising Clock Edge ( )
L	Χ	Χ	Χ	RESET (Clear)
Н	L	Χ	Χ	LOAD $(P_n \rightarrow Q_n)$
Н	Н	Н	Н	COUNT (Increment)
Н	Н	L	Χ	NO CHANGE (Hold)
Н	Н	Χ	L	NO CHANGE (Hold)

\*For the LS163A only.

H = HIGH Voltage Level L = LOW Voltage Level

X = Don't Care

LS161A
DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (unless otherwise specified)

		Limits					
Symbol	Parameter	Min	Тур	Max	Unit	Tes	t Conditions
VIH	Input HIGH Voltage	2.0			V	Guaranteed Input All Inputs	t HIGH Voltage for
V <sub>IL</sub>	Input LOW Voltage			0.8	٧	Guaranteed Input All Inputs	t LOW Voltage for
V <sub>IK</sub>	Input Clamp Diode Voltage		-0.65	-1.5	V	V <sub>CC</sub> = MIN, I <sub>IN</sub> =	: –18 mA
VOH	Output HIGH Voltage	2.7	3.5		٧	V <sub>CC</sub> = MIN, I <sub>OH</sub> = MAX, V <sub>IN</sub> = V <sub>IH</sub> or V <sub>IL</sub> per Truth Table	
			0.25	0.4	V	I <sub>OL</sub> = 4.0 mA	V <sub>CC</sub> = V <sub>CC</sub> MIN,
VOL	Output LOW Voltage		0.35	0.5	V	I <sub>OL</sub> = 8.0 mA	V <sub>IN</sub> = V <sub>IL</sub> or V <sub>IH</sub> per Truth Table
IIH	Input HIGH Current  MR, Data, CEP, Clock PE, CET			20 40	μА	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 2.7 V	
-111	MR, Data, CEP, Clock PE, CET			0.1 0.2	mA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 7.0 V	
IIL	Input LOW Current MR, Data, CEP, Clock PE, CET			-0.4 -0.8	mA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 0.4 V	
los	Short Circuit Current (Note 2)	-20		-100	mA	V <sub>CC</sub> = MAX	
ICC	Power Supply Current Total, Output HIGH Total, Output LOW			31 32	mA	V <sub>CC</sub> = MAX	

<sup>2.</sup> Not more than one output should be shorted at a time, nor for more than 1 second.

#### LS163A

#### DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (unless otherwise specified)

		Limits					
Symbol	Parameter	Min	Тур	Max	Unit	Tes	t Conditions
VIH	Input HIGH Voltage	2.0			V	Guaranteed Input All Inputs	HIGH Voltage for
V <sub>IL</sub>	Input LOW Voltage			0.8	٧	Guaranteed Input All Inputs	LOW Voltage for
VIK	Input Clamp Diode Voltage		-0.65	-1.5	V	V <sub>CC</sub> = MIN, I <sub>IN</sub> =	: –18 mA
VOH	Output HIGH Voltage	2.7	3.5		٧	$V_{CC}$ = MIN, $I_{OH}$ = MAX, $V_{IN}$ = $V_{IH}$ or $V_{IL}$ per Truth Table	
			0.25	0.4	V	I <sub>OL</sub> = 4.0 mA	V <sub>CC</sub> = V <sub>CC</sub> MIN,
VOL	Output LOW Voltage		0.35	0.5	V	I <sub>OL</sub> = 8.0 mA	V <sub>IN</sub> = V <sub>IL</sub> or V <sub>IH</sub> per Truth Table
IIH	Input HIGH Current <u>Data</u> , CEP, Clock PE, CET, SR			20 40	μΑ	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 2.7 V	
""	<u>Da</u> ta, CEP <u>, C</u> lock PE, CET, SR			0.1 0.2	mA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 7.0 V	
IIL	Input LOW Current Data, CEP, Clock, PE, SR CET			-0.4 -0.8	mA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 0.4 V	
los	Short Circuit Current (Note 3)	-20		-100	mA	V <sub>CC</sub> = MAX	
ICC	Power Supply Current Total, Output HIGH Total, Output LOW			31 32	mA	V <sub>CC</sub> = MAX	

<sup>3.</sup> Not more than one output should be shorted at a time, nor for more than 1 second.

#### AC CHARACTERISTICS $(T_A = 25^{\circ}C)$

			Limits			
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
fMAX	Maximum Clock Frequency	25	32		MHz	
tPLH tPHL	Propagation Delay Clock to TC		20 18	35 35	ns	
<sup>t</sup> PLH <sup>t</sup> PHL	Propagation Delay Clock to Q		13 18	24 27	ns	$V_{CC} = 5.0 \text{ V}$ $C_L = 15 \text{ pF}$
<sup>t</sup> PLH <sup>t</sup> PHL	Propagation Delay CET to TC		9.0 9.0	14 14	ns	
<sup>t</sup> PHL	MR or SR to Q		20	28	ns	

#### AC SETUP REQUIREMENTS $(T_A = 25^{\circ}C)$

			Limits			
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
t <sub>W</sub> CP	Clock Pulse Width Low	25			ns	
t₩	MR or SR Pulse Width	20			ns	
t <sub>S</sub>	Setup Time, other*	20			ns	
t <sub>S</sub>	Setup Time PE or SR	25			ns	V <sub>CC</sub> = 5.0 V
t <sub>h</sub>	Hold Time, data	3			ns	
t <sub>h</sub>	Hold Time, other	0			ns	
t <sub>rec</sub>	Recovery Time MR to CP	15			ns	

<sup>\*</sup>CEP, CET, or DATA

#### **DEFINITION OF TERMS**

SETUP TIME  $(t_S)$  — is defined as the minimum time required for the correct logic level to be present at the logic input prior to the clock transition from LOW to HIGH in order to be recognized and transferred to the outputs.

HOLD TIME (th) — is defined as the minimum time following the clock transition from LOW to HIGH that the logic level must be maintained at the input in order to ensure

continued recognition. A negative HOLD TIME indicates that the correct logic level may be released prior to the clock transition from LOW to HIGH and still be recognized.

RECOVERY TIME  $(t_{rec})$  — is defined as the minimum time required between the end of the reset pulse and the clock transition from LOW to HIGH in order to recognize and transfer HIGH Data to the Q outputs.

#### **AC WAVEFORMS**

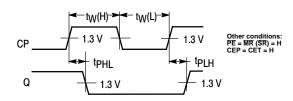


Figure 1. Clock to Output Delays, Count Frequency, and Clock Pulse Width

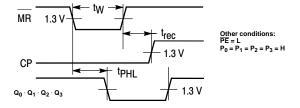


Figure 2. Master Reset to Output Delay, Master Reset Pulse Width, and Master Reset Recovery Time

#### **AC WAVEFORMS (continued)**

#### **COUNT ENABLE TRICKLE INPUT** TO TERMINAL COUNT OUTPUT DELAYS

The positive TC pulse occurs when the outputs are in the (Q0 • Q<sub>1</sub> • Q<sub>2</sub> • Q<sub>3</sub>) state for the LS161 and LS163.

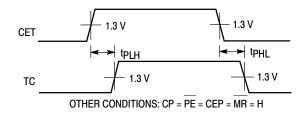


Figure 3.

#### **CLOCK TO TERMINAL COUNT DELAYS**

The positive TC pulse is coincident with the output state  $(Q_0 \bullet Q_1 \bullet Q_2 \bullet Q_3)$  for the LS161 and LS163.

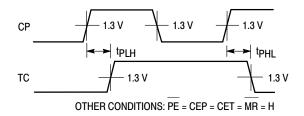


Figure 4.

#### SETUP TIME (t<sub>S</sub>) AND HOLD TIME (t<sub>h</sub>) FOR PARALLEL DATA INPUTS

The shaded areas indicate when the input is permitted to change for predictable output performance.

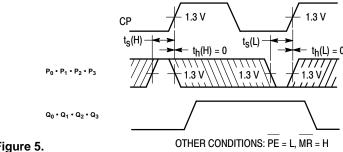


Figure 5.

#### SETUP TIME (ts) AND HOLD TIME (th) FOR COUNT ENABLE (CEP) AND (CET) AND PARALLEL ENABLE (PE) INPUTS

The shaded areas indicate when the input is permitted to change for predictable output performance.

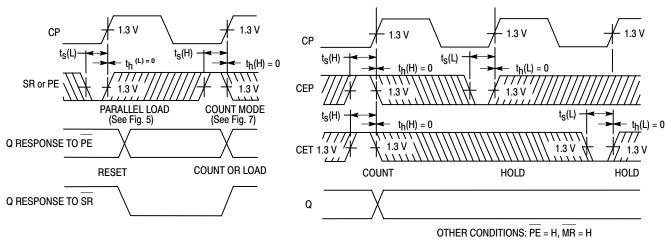
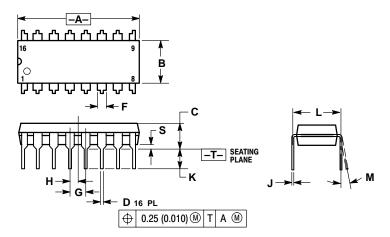


Figure 6. Figure 7.

#### **PACKAGE DIMENSIONS**

#### **N SUFFIX**

PLASTIC PACKAGE CASE 648-08 ISSUE R

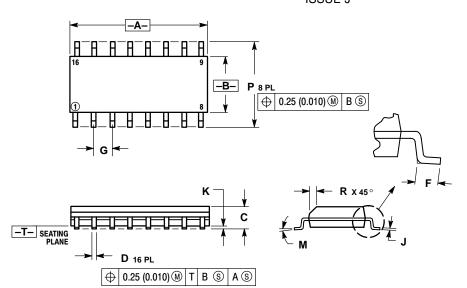


- NOTES:
  1. DIMENSIONING AND TOLERANCING PER ANSI
- DIMENSIONING AND TOLERANGING FER AN.

  Y14.5M, 1982.
  CONTROLLING DIMENSION: INCH.
  DIMENSION L TO CENTER OF LEADS WHEN
  FORMED PARALLEL.
- DIMENSION B DOES NOT INCLUDE MOLD FLASH.
   ROUNDED CORNERS OPTIONAL.

	INC	HES	MILLIN	IETERS	
DIM	MIN	MAX	MIN	MAX	
Α	0.740	0.770	18.80	19.55	
В	0.250	0.270	6.35	6.85	
С	0.145	0.175	3.69	4.44	
D	0.015	0.021	0.39	0.53	
F	0.040	0.70	1.02	1.77	
G	0.100	BSC	2.54 BSC		
Н	0.050	BSC	1.27 BSC		
J	0.008	0.015	0.21	0.38	
K	0.110	0.130	2.80	3.30	
L	0.295	0.305	7.50	7.74	
M	0°	10 °	0°	10 °	
S	0.020	0.040	0.51	1.01	

#### **D SUFFIX** PLASTIC SOIC PACKAGE CASE 751B-05 **ISSUE J**



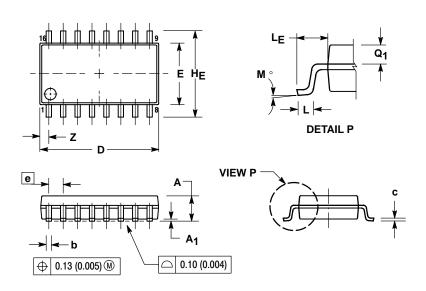
- NOTES: 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- Y14-3M, 1982.
  CONTROLLING DIMENSION: MILLIMETER.
  DIMENSIONS A AND B DO NOT INCLUDE
  MOLD PROTRUSION.
  MAXIMUM MOLD PROTRUSION 0.15 (0.006)
- PER SIDE.
  DIMENSION D DOES NOT INCLUDE DAMBAR
- DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIN	IETERS	INC	HES	
DIM	MIN MAX		MIN	MAX	
Α	9.80	10.00	0.386	0.393	
В	3.80	4.00	0.150	0.157	
С	1.35	1.75	0.054	0.068	
D	0.35	0.49	0.014	0.019	
F	0.40	1.25	0.016	0.049	
G	1.27	BSC	0.050 BSC		
J	0.19	0.25	0.008	0.009	
K	0.10	0.25	0.004	0.009	
M	0°	7°	0°	7°	
P	5.80	6.20	0.229	0.244	
R	0.25	0.50	0.010	0.019	

#### PACKAGE DIMENSIONS

#### **M SUFFIX**

SOEIAJ PACKAGE CASE 966-01 **ISSUE O** 



#### NOTES:

- 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- CONTROLLING DIMENSION: MILLIMETER.
  DIMENSIONS D AND E DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS AND ARE MEASURED AT THE PARTING LINE MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.15 (0.006) PER SIDE
- TERMINAL NUMBERS ARE SHOWN FOR
- REFERENCE ONLY.
  THE LEAD WIDTH DIMENSION (b) DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08 (0.003) TOTAL IN EXCESS OF THE LEAD WIDTH DIMENSION AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSIONS AND ADJACENT LEAD TO BE 0.46 ( 0.018)

	MILLIMETERS		INCHES	
DIM	MIN	MAX	MIN	MAX
Α		2.05		0.081
A <sub>1</sub>	0.05	0.20	0.002	0.008
b	0.35	0.50	0.014	0.020
u	0.18	0.27	0.007	0.011
D	9.90	10.50	0.390	0.413
Е	5.10	5.45	0.201	0.215
е	1.27 BSC		0.050 BSC	
HE	7.40	8.20	0.291	0.323
L	0.50	0.85	0.020	0.033
LE	1.10	1.50	0.043	0.059
M	0 °	10°	0 °	10 °
Q <sub>1</sub>	0.70	0.90	0.028	0.035
Z		0.78		0.031

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